



Implementation of CBCS / ECS

Minutes of Meetings (MoM) of Board of Studies (BoS)

Academic Year: 2021-22

School : School of Studies of Engineering and Technology

Department : Industrial and Production Engineering

Date and Time: October 29, 2021 - 03:00 PM

Venue : Online

The scheduled meeting of member of Board of Studies (BoS) of Department of Industrial and Production Engineering, School of Studies of Engineering and Technology, Guru Ghasidas Vishwavidyalaya, Bilaspur was held to design and discuss the B. Tech. Fourth year (VII and VIII semesters) scheme and syllabi.

The following members were present in the meeting:

- 1. Prof. G.K. Agrawal (External Expert Member BoS, Professor, GEC Bilaspur)
- 2. Mr. Dalbir Singh Rekhi (Member BoS Industry Expert, J.S.P.L. Raigarh CG.)
- 3. Prof. Mukesh Kumar Singh (Member BoS, Professor, Dept. of Industrial and Production Engineering)
- 4. Prof. S.C. Srivastava (HOD, Prof., Dept. of Industrial and Production Engineering-cum Chairman, BOS)
- 5. Mr. C.P. Dewangan (Member BoS, Associate Professor, Dept. of Industrial and Production Engineering)
- 6. Mrs. Disha Dewangan (Member BoS, Assistant Professor, Dept. of Industrial and Production Engineering)
- 7. Mrs. Arpita Roy Choudhary (Invited Member, Professor, Dept. of Industrial and Production Engineering)
- 8. Dr. Atul Kumar Sahu (Invited Member, Assistant Professor, Dept. of Industrial and Production Engineering)
- 9. Mr. Ganesh Prasad Shukla (Invited Member, Assistant Professor, Dept. of Industrial and Production Engineering)
- 10. Mr. Nitin Kumar Sahu (Invited Member, Assistant Professor, Dept. of Industrial and Production Engineering)
- 11. Mr. Leeladhar Rajput (Invited Member, Assistant Professor, Dept. of Industrial and Production Engineering).
- 12. Mr. Kawal Lal Kurrey (Invited Member, Assistant Professor, Dept. of Industrial and Production Engineering).
- 13. Mr. Anurag Singh (Invited Member, Assistant Professor, Dept. of Industrial and Production Engineering).
- 14. Mr. Somnath Singroul (Invited Member, Assistant Professor, Dept. of Industrial and Production Engineering).





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Following points were discussed during the meeting

- 1. In the meeting, Choice Based Credit System(CBCS) scheme and syllabus of M.Tech CAD-CAM and Robotics (Industrial and Production Engineering) were discussed in details. All suggestion of the members are incorporated and modified and then recommended for approval.
- 2. The CBCS scheme and syllabus of M.Tech CAD-CAM and Robotics (Industrial and Production Engineering) have been accepted by the BOS (I.P.E.)

The following new courses were introduced in the of M.Tech CAD-CAM and Robotics :

- 1. COMPUTER AIDED DESIGN (IPPATT1)
- 2. FUNDAMENTALS OF ROBOTICS (IPPATT2)
- 3. COMPUTER INTEGRATED MANUFACTURING (IPPATP1)
- 4. RAPID PROTOTYPING AND TOOLING (IPPATP2)
- 5. SUPPLY CHAIN MANAGEMENT (IPPATP3)
- 6. ADVANCED MANUFACTURING PROCESSES (IPPATP4)
- 7. MECHANICS OF SHEET METAL FORMING (IPPATP5)
- 8. MICRO-MANUFACTURING (IPPATP6)
- 9. MODELING & SIMULATION (IPPATP7)
- 10. THEORY OF VIBRATION (IPPATP8)
- 11. ARTIFICIAL INTELLIGENCE (IPPATP9)
- 12. RESEARCH METHODOLOGY& IPR (IPPATC1)
- 13. CAD-CAM LAB (IPPALT1)
- 14. FINITE ELEMENT ANALYSIS (IPPBTT1)
- 15. ROBOTICS AND CONTROL (IPPBTT2)
- 16. GREEN MANUFACTURING (IPPBTP1)
- 17. ADVANCE OPERATION RESEARCH (IPPBTP2)
- 18. TOTAL QUALITY MANAGEMENT (IPPBTP3)
- 19. MECHANICS OF COMPOSITE MATERIAL (IPPBTP4)
- 20. SMART MATERIALS AND APPLICATIONS (IPPBTP5)
- 21. MECHATRONICS IN MANUFACTURING SYSTEMS (IPPBTP6)
- 22. BUSINESS ANALYTICS (MSPBTO1)
- 23. INDUSTRIAL SAFETY (IPPBTO2)
- 24. OPERATIONS RESEARCH (IPPBTO3)
- 25. COST MANAGEMENT OF ENGINEERING PROJECTS (CEPBTO4)
- 26. COMPOSITE MATERIALS (MEPBTO5)
- 27. WASTE TO ENERGY (CHPBTO6)
- 28. IOT (ECPBTO7)
- 29. MOOCS (MCPBTO8)
- 30. ENGLISH FOR RESEARCH PAPER WRITING (ELPBTX1)
- 31. STRESS MANAGEMENT BY YOGA (PEPBTX2)
- 32. DISASTER MANAGEMENT (CEPBTX3)
- 33. CONSTITUTION OF INDIA (LAPBTX4)
- 34. MINI PROJECT/SEMINAR (IPPBPT1)
- 35. ROBOTICS LAB (IPPBLT1)
- 36. DISSERTATION STAGE-I (IPPCPT1)



37. DISSERTATION STAGE-II (IPPDPT1)

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Signature & Seal of HoD





Scheme and Syllabus



GURU GHASIDAS VISHWAVIDYALAYA BILASPUR (C.G.)

(A Central University) Koni, Bilaspur-495009, C.G (India)



OUTCOME BASED EDUCATION WITH CHOICE BASED CREDIT SYSTEM (CBCS)

MASTER OF TECHNOLOGY IN CAD-CAM AND ROBOTICS

COURSE STRUCTURE AND SYLLABI

M.Tech. Regular Two Year Degree Program (Effective from the academic year 2021-22)

DEPARTMENT OF INDUSTRIAL & PRODUCTION ENGINEERING SCHOOL OF ENGINEERING &TECHNOLOGY, GGV, BILASPUR, C.G. (INDIA)

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With effect from Academic Year 2021-22

DEPARTMENT OF INDUSTRIAL & PRODUCTION ENGINEERING SCHOOL OF ENGINEERING & TECHNOLOGY, GGV, BILASPUR, C.G. (INDIA) SCHEME OF EXAMINATION

M.TECH, CAD-CAM and ROBOTICS

M.Tech. I-Semester

| SL | Course Type/ | | Subjects | Peri | ods/V | čeck. | E | Credits | | |
|----|-------------------------------|----------|--|------|-------|-------|-----|---------|-------|----|
| | Code | | | E | T | r | LA | ESE | Total | |
| 1. | UPPATTI | | Computer Aided Design | 3 | 0 | 0 | 40 | 60 | 100 | 3 |
| 2. | IPPATT2 | | Fundamentals of Robotics | 3 | 0 | 0 | 40 | 68 | 100 | 3 |
| 3. | IPPATPI IPPATP3 | 1. 2. 3. | Elective—I Computer Integrated Manufacturing Rapid Prototyping and Tooling Supply chain management | 3 | 0 | .0 | 49 | 69 | 100 | 3 |
| 4. | IPPATPS IPPATPS | 2 | Elective - II Advanced Manufacturing Processes Mechanics of Sheet Metal Forming Micro-manufacturing | a | | 0 | 40 | 68 | 100 | 3 |
| S. | IPPATP? IPPATPS IPPATPS | 1 | Elective - III Modeling & Simulation Theory of Vibration Artificial Intelligence | 3 | .0 | 9 | 40 | 60 | 100 | 3 |
| 6. | IPPATC1 | | Research Methodology& IPR | 2 | 0 | ò | - | 50 | 50 | 2 |
| 7. | IPPALTI | | CAB-CAM bb | | 0 | 4 | 30 | 20 | 50 | 2 |
| | | | Total | 17 | 0 | 4 | 230 | 379 | 600 | 19 |

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With effect from Academic Year 2021-22

M.TECH. CAD-CAM and ROBOTICS

M.Tech. II-Semester

| 81. | Course | Subjects | Peri | ods/V | Veck | . 1 | value: | History | Credit |
|-----|-------------------------------|---|------|-------|------|-----|--------|---------|--------|
| | Type/ Code | | L | T | P | IA | ESE | Total | |
| L | IPPBTII | Finite Element Analysis | 3 | 0 | 0 | 40 | 60 | 190 | 3 |
| | IPPBTT2 | Robotics and Control | 3 | 0 | 0 | 40 | 60 | 100 | 3 |
| ٥. | | Elective IV | 3 | 0 | 0 | 40 | 60 | 100 | 3 |
| | IPPBTP1 IPPBTP2 IPPBTP3 | Green Manufacturing Advance Operation Research Total Quality Management | | | | | | | |
| 6. | | Elective - V | 3 | 0 | 0 | 40 | 60 | 100 | 3 |
| | IPPB174 | 1. Mechanics of Composite Material | | | | | | | |
| | IPPRIPS | 2. Smart Materials and Applications | | | | | | | |
| | IPPBTPs | 3. Mechalronics in Manufacturing Systems | | | | | | | |
| 5. | | Open Elective | 3 | 0 | 0 | 40 | 60 | 100 | 3 |
| | MSPRIOI IPPRIO2 | 1. Business Analytics 2. Industrial Safety | | | | | | | |
| | IPPBTO3 | J. Operations Research | | | | | | | |
| | CEPBTO4 | 4. Cost Management of Engineering Projects | | | | | | | |
| | MEPRIOS | 5. Composite Materials | | | | | | | |
| | ECFRIO7 | 6. Waste to Energy 7. IoT | | | | | | | |
| | MCPBTO8 | 8. MOOCs | | | | | | | |
| h | | Audii Caurse/Value Added Course | 2 | 0 | 0 | 0 | 0 | 9 | 0 |
| | ELPRIXI | English for Research Paper Writing | | | | | | | |
| | PEPBIX2 | Stress Management by Yoga | | | | | | | |
| | LAPBTX4 | Disaster Management Constitution of India | | | | | | | |
| | IPPRPT1 | Mint Project/Seminar | | 0 | • | 39 | 28 | 50 | 2 |
| | IPPBLTI | Robitics lab | 0 | 0 | 4 | 30 | 20 | 50 | 2 |
| | | Total | 17 | 0 | 608 | 260 | 340 | 600 | 19 |

Note: Under MOOCs the students have to opt any subject other than Industrial & Production Engineering from NPTEL/UGC SWAYAM



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M.TECH, CAD-CAM and ROBOTICS

M.Tech. III-Semester

| SL | Course Type: | - C-1 | Peri | Periods/Week | | | | Evaluation | | | |
|----|--------------|---|------|--------------|----|-----|-----|------------|----|--|--|
| | Code | (a-c) | L | T | P | LA | ESE | Total | | | |
| 1. | IPPCPTI | Dissertation Stage I | 0 | 0 | 28 | 100 | 100 | 200 | 14 | | |
| | | Total | 0 | 0 | 28 | 100 | 100 | 200 | 14 | | |

M.TECH. CAD-CAM and ROBOTICS

M.Tech. IV-Semester

| SL | Course Typer | Subjects | Peri | Periods/Week | | | | Evaluation | | | |
|----|--------------|-----------------------|------|--------------|----|-----|-----|------------|----|--|--|
| | Code | =(0)= | L | T | P | LA | ESE | Total | | | |
| i. | IPPOPTI | Dissertation Stage-II | 0 | 0 | 32 | 100 | 200 | 300 | 18 | | |
| | | Total | 0 | 0 | 30 | 100 | 200 | 300 | 18 | | |

Total Credits for the Program = 19 + 19 +14 +18 = 70

| Course | Subjects | Periods/Werk Evaluation | | | | | Credits | |
|----------|-----------------------|-------------------------|---|----|----|-----|---------|---|
| Code | | L | T | P | IA | ESE | Total | |
| IPPATTI. | Computer Aided Design | 9 | 0 | .0 | 40 | 60 | 100 | 3 |

IPPATTI- COMPUTER AIDED DESIGN

Course Objectives

The objective of this course is to;

- Get idea of basic fundamentals of computer graphics used in CAD hardware and software and its communications.
- Introduce various algorithms and mathematical expressions of curves, surface and solid CAD model.
- Impart knowledge of new design concept and optimization technique to generate surface and solid in CAD:
- Introduce basic fundamental of finite element method (FEM) for design optimization of mechanical element.

Course Outcomes

After successful completion of this course studentsure able to:

- Generate and interpret engineering design of mechanical parts according to engineering design standards and its role in graphic communication process.
- 2. Impart knowledge ofconceptual understanding of the principles of CAD systems, the



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implementation of these principles, and its connections to CAE systems.

- Comprehend the coordinate representation of 2-D and 3-D entity and formulate the geometric transformations and its projections.
- Get knowledge of mathematical representations of curves, surface and solid model and analysis
 of designed object.
- 5. Analyze the solid model and able to calculate its property through basic fundamental of FEM:

COURSE CONTENTS

Module 1

Introduction and progressive development of CAD, CAD system evaluation criteria, hardware and software, hardware integration and networking, computer communication color management and raster graphics, aliasing and anti-aliasing, lines, circle and ellipse algorithms, windowing, clipping and view port.

Module 2

Coordinate systems, fundamental of geometric transformations, homogeneous representations, concatenation and composite transformations, 2-D and 3-D geometric transformations, orthographic and oblique projections.

Module 3

Basics of curves, parametric and non-parametric curves, analytical and synthetic curves, parametric representation of analytical and synthetic curves, Hermite curves, curve manipulations, Bézier curves, B-splines, rational curves, wire frame models.

Module 4

Mathematical representation of surfaces, analytical and synthesis surfaces, parametric representation of surfaces such as, plane surface, tabulated surface, revolve surface, ruled surface, coon's patch, bi-linear surface, Herunte bi-cubic surface, Furguson surface, Bézier surface patch, B-Spline surface patch, NURBS surface patch.

Module 5

Progressive development and fundamental of solid modeling, solid primitives, primitive instancing (PI), set theories, regularized Booleans set operation (RBSO), constructive solid geometry (CSG), boundary representation (B-rep), sweep representations (SR), spatial occupancy emmeration, cellular and octave decomposition (CD), analytic solid modeling (ASM), introduction to finite element method (FEM), 1-D FEM analysis.

Text Books & References

1. Zeid I & Subramanian R. S., CAD/CAM Theory and practice, Tata McGraw Hill.



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- Zeid I., Mastering CAD/CAM, McGraw Hill International.
- 3. Groover M.P. &Zimmers E., CAD/CAM: Computer-Aided Design and Manufacturing,
- 4. Pearson Education.
- 5. Rao P. N., CAD/CAM Principles and Applications, Tata McGraw Hill.
- 6. Alavala, CAD/CAM Concepts and Applications, Prentice Hall of India.
- 7. Krishnamurthy N., Introduction to Computer Graphics, Tata McGraw Hill.
- 8. NewmanW.M.&Sproull R.F., Principles of Interactive Computer Graphics, Tata McGraw Hill.

| Course | Subjects | Periods/Week | | | 1 | Product. | Credits | |
|---------|--------------------------|--------------|---|--|----|----------|---------|---|
| Code | | L | T | | LA | ES E | Tota | |
| IPPATT2 | Fundamentals of Robotics | 3 | 0 | | 40 | 60 | 200 | 3 |

IPPATT2-FUNDAMENTALS OF ROBOTICS

Course Objective

The objective of this course is to:

- 1. Provide the concept of automation and robots and its challenges in real world environment.
- 2. Introduce the concept of drives, actuators, sensors and machine vision used in robotics.
- 3. Impart knowledge of the gripper and control aspects of the robotic systems.
- Introduce the working principles of intelligent autonomous vehicle (IAV) and quad-mints unmanned serial vehicle (QUAV).

Course Outcome

At the end of the course students will be able to:

- Learn basic concepts associated with automation and robotics and aware of recent updates in robotics.
- 2. Recognize the application of various drives and actuators used in robotic system.
- 3. Understand the basic concept of sensors and machine vision system used in robotic system.
- 4 Acquire knowledge of working principles of grippers and control system used in robotics
- Learn concept of intelligent autonomous vehicle (IAV) and quad-rotors unmanned serial vehicle (QUAV) used in industries and non-industries.

COURSE CONTENTS

Module-E

Automation concept and need, principles and strategies of automation, basic elements of an automated system, levels of automations, advanced automation functions, numeric control machine and robots, robot mutomy and classifications, laws of robotics, accuracy and repeatability, challenges of various robots, typical industrial and non-industrial applications of



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robots.

Module -2

Introduction of robot drives and actuators, functions and classification of drive and actuator systems, selection of drives and actuators, pneumatic and hydraulic drives, motors used in robotics, arrangement of actuators in robots, error response, feedback and feed forward compensations, modeling of robot servos, computer controlled servo systems, selection of robot drives and actuators.

Module -3

Introduction to sensors and transducers, characteristicsand requirements of sensing devices, classifications and functions of sensors and transducers, various types of sensors, robot guidance with vision system, vision system devices, image acquisition, masking, sampling and quantization, image processing techniques, edge detection, segmentation, calibration of sensors and multisensory-controlled robot.

Module 4

Design aspect of gripper, functions and types of grippers, force analysis for various basic gripper systems, characteristics of control systems, types of controllers, open and closed loop control, robot and industrial control systems, continuous verses discrete control, control systems components, motion interpolation, WAIT, SIGNAE and DELAY commands, subroutines, introduction to various types such as RAIL and VAL II etc. finitures of type and development of languages for recent robot systems.

Module 5

Introduction of autonomous mobile robots (AMR) and quad-rotors unmanned serial vehicles (QUAV), holonomic and non-holonomic, sensing and control, navigation algorithms, stability and controllability of intelligent automated vehicles (IAV) and QUAV, driver assistance and monatoring systems, road scene interpretation, need and necessity of IAV and QUAV, industrial and non-industrial applications of IAV and QUAV.

Text Books & References

- John J. Craig, "Introduction to robotics", Addison Wesley Longman.
- 2. Nagrath LJ. & Mittal R.K., "Robotics &Control" Tata McGraw Hill.
- 3. Murphy, "Introduction of AI robotics", MIT press.
- Siegwart R., Nourbaklish I.R. & Scaramuzza D., "Introduction to Autonomous Mobile Robots", MIT press.
- 5. Rogelio Lozano, "Unmanned Aerial Vehicles: Embedded Control", Wiley Publisher.
- Greeth J., Monkman, Stefan H., Ralf S. & Heurik S., "Robot Grippers", Wiley Publisher.

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|---------|---|--------------|---|---|-----|--------|---------|---|
| Code | | L | T | P | IA. | ESE | Total | |
| | Elective - 1 | 3 | 0 | 0 | 40 | 63 | 100 | 3 |
| IPPATP1 | 1. Computer Integrated Manufacturing | | | | | | | |
| BPATP2 | 2. Rapid Protetyping and Tooling | | | | | | | |
| IPPATP3 | 3. Additive Manufacturing Technologies | | | | | | | |

IPPATPI COMPUTER INTEGRATED MANUFACTURING

Course Objectives:

The objective of this course is to

- Emphasize the integration of manufacturing enterprise using computer-integrated manufacturing (CIM) technologies.
- Employ CAD/CAM interface and other CIM subsystems.
- Develop database management, facility layout, Group technology, teamwork, and manufacturing operations.

Course Outcomes:

At the end of the course students will be able to

- Develop an understanding of computer-integrated manufacturing (CIM) and its impact on productivity, product cost, and quality.
- Obtain an overview of computer technologies including computers, database and datacellection, networks, machine control, etc., as they apply to factory management and factory floor operations.
- Describe the integration of manufacturing activities into a complete system.

COURSE CONTENTS

Module-1

Introduction: Evolution of CIM, scope of CIM, segments of generic CIM, Automated Process Planning-Process planning, group technology, variant and generative process planning methods, Alin processplanning process planning software. CNC technology - Principles of immerical control, features of CNC systems, programming techniques, capabilities of a typical NC CAM software, integration of CNC machines in CIM environment, DNC - Flexible manufacturing systems. Architecture, work stations.

Module-2

Manufacturing Systems: MRP II software, production control software, forecasting, masterproductionschedule, materials requirements planning, capacity requirements planning, shop floor control, shop floor data collection techniques, inventory management, purchase orders, bill of materials, standard product routing, sob costing, marketing applications.



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Module-3

Robotics, Automated Assembly and Inspection. Types of robots and their performance capabilities programming of robots, hardware of robots, kinematics of robots, product design for robotized manufacturing, selecting assembly machines, feeding and transfer offarts, applications of robots in manufacture and assembly, sensors. Automated quality control types of CMM, non-contact inspection methods, in process and post process metrology, flexible inspection systems.

Computer Added Inspection and on-line quality monitoring.

Module-4

Data Communications and Technology Management: Technology issues, configuration management, database systems, management of technology, networking concepts, Local area Network (LAN), SQL fundamentals, Manufacturing Automation protocols (MAP) and Technical and office protocols (TOP) fundamentals—CIM models, economics of CIM, implementation of CIM.

Module-5

Collaborative Engineering: Introduction, Faster Design throughput, Web based design, Changing design approaches, extended enterprises, concurrentengineering, supply chain management (SCM), Customeroelatious management(CRM) Virtual Reality and Factory simulation, Agile and Jean manufacturing, reverse engineering, Rapid prototyping.

Text Books & References

- Manufacturing Engineering and Technology SeropeKalpak Jain, and Steven R. Smith, Pearsoneducation.
- Automation, Production systems and Computer Integrated Manufacturing System-Mikell P.Groover, PHI Publication.
- Computer Integrated Manufacturing Hand Book EricTeicholz and Joel Orr, McGraw Hill Publication.
- Computer Integrated Manufacturing Paul G. Ranky, CIMware Publishers.
- CAD / CAM / CIM Radhakrishnau, New Age International Publication.

IPPATP2 RAPID PROTOTYPING AND TOOLING

Course Objectives

The objective of this course is to

- Familiarize the basic concepts of RPT.
- Recognize various process in RP
- Analyze the principles of Rapid tooling and reverse Engineering.

Course outcome



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After completion of the course, the students will be able to:

- Use different techniques for processing of CAD models for rapid prototyping.
- Apply fundamentals of rapid prototyping techniques.
- Use appropriate tooling for rapid prototyping process.
- Develop different rapid prototyping techniques for reverse engineering.

COURSE CONTENTS

Module 1

Introduction to Prototyping: Traditional Prototyping Vs. Rapid Prototyping (RP), Need for time compression in product development, Usage of RP parts, Generic RP process, Distinction between RP and CNC, other related technologies, Classification of RP.

Module 2

Liquid-based Rapid Prototyping Systems Stereo lithography Apparatus (SLA) Models and specifications. Process, working principle, photopolymers, photo polymerization, Layering technology, laser and laser scanning. Applications, Advantages and Disadvantages, Case studies. Solid ground curing (SGC) Models and specifications, Process, working principle, Applications, Advantages and Disadvantages, Case studies Solid-based Rapid Prototyping Systems: Laminated Object Manufacturing (LOM): Models and specifications, Process, working principle, Applications, Advantages and Disadvantages, Case studies. Fused Deposition Modeling (FDM): Models and specifications, Process, working principle, Applications, Advantages and Disadvantages, Case studies.

Module 3

Powder Based Rapid Prototyping Systems: Selective laser sintering (SLS): Models and specifications, Process, working principle, Applications, Advantages and Disadvantages, Case studies. Three dimensional Printing (3DP): Models and specifications, Process, working principle, Applications, Advantages and Disadvantages, Case studies. Rapid Tooling: Introduction to Rapid Tooling (RT), Conventional Tooling Vs. RT, Need for RT. Rapid Tooling Classification: Indirect Rapid Tooling Methods: Spray Metal Deposition, RTV Epoxy Tools, Certaine tools, Investment Casting, Spin Casting, Die casting, Sand Casting, 3D Keltool process. Direct Rapid Tooling Direct AIM, LOM Tools, DTM Rapid Tool Process, EOS Direct Tool Process and Direct Metal Tooling using 3DP.

Module 4

Rapid Prototyping Data Formats: STL Format, STL File Problems, Consequence of Building Valid and Invalid Tessellated Models, STL file Repurs: Generic Solution, Other Translators, Newly Proposed Formats. Rapid Prototyping Software's: Features of various RP software's like Magic's, Mimics, Solid View, View Expert, 3 D View, Velocity 2, Rhino, STL View 3 Data Expert and 3 D doctor.



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Module 5

RP Applications: Application: Material Relationship, Application in Design., Application in Engineering, Analysis and Planning, Aerospace Industry, Automotive Industry, Jewellery Industry, Coin Industry, GIS application, Arts and Architecture. RP Medical and Bioengineering Applications: Planning and simulation of complex surgery, Customized Implants & Prosthesis, Design and Production of Medical Devices, Forensic Science and Authropology, Visualization of Bio-molecules.

Text Books & References

- Chun C K, Leong K F, Chu S L, Rapid Prototyping: Principles and Applications in Manufacturing, World Scientific.
- Gibson D W Rosen, Brent Stucker., Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing. Springer.
- Noorani R, Rapid Prototyping: Principles and Applications in Manufacturing, John Wiley & Sons.
- 4. Hilton P, Jacobs P F, Rapid Teoling: Technologies and Industrial Applications, CRC press.
- Liou W L, Liou F W, Rapid Prototyping and Engineering applications: A tool box for prototype development, CRC Press.
- Kamrani A K, Nasr E A, Rapid Prototyping: Theory and practice, Springer.

IPPATP3 SUPPLY CHAIN MANAGEMENT

Course Objectives

The objective of this course is to

- I To define supply clain, its importance and management.
- To categorize various drivers of Supply Chain for grasping effectual performance.
- To understand about uncertainty, risk management and forecasting.
- To outline Competitive advantages, Distribution Networks and Supply Chain Strategies
- 5. To elaborate drivers and barriers of Distribution Networks in Practice.

Course Outcomes

After the completion of this course, students will be:

- Demonstrate a basic understanding about Competition and Supply Chain Strategies
- Acquire knowledge about distribution network, E-Business and Time-Series
- Demonstrate technical understanding about demand, inventory, safety, pricing.
- Implement decision making policies, infrastructure and optimum Design for handling. Transportation Network.
- 5 Resolve uncertain and risk decision in decision making and can capably tralored



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transportation and supply chain costs.

COURSE CONTENTS

Module 1

Building a Strategic Framework to Analyze Supply Chains: What Is a Supply Chain? The Objective of a Supply Chain, The Importance of Supply Chain Decisions, Decision Phases in a Supply Chain, Process View of a Supply Chain, Examples of Supply Chains, Supply ChainPerformance, Achieving Strategic Fit and Scope, Competitive and Supply Chain Strategics, Achieving Strategic Fit, Expanding Strategic Scope, Supply Chain Drivers and Metrics, Drivers of Supply Chain Performance, framework for Structuring Drivers, Facilities, Inventory, Transportation, Information, Sourcing, Pricing.

Module 2

Designing the Supply Chain Network: Designing Distribution Networks and Applications to e-Business the Role of Distribution in the Supply Chain. Factors Influencing DistributionNetwork, Design, Design Options for a Distribution Network, e-Business and the DistributionNetwork, Distribution Networks in Practice.

Network Design in the Supply Chain: The Role of Network Design in the Supply Chain, Factors Influencing Network Design Decisions Framework for Network Design Decisions, Models for Facility Location and Capacity Allocation, The role of IT in Network Design, Making Network Design Decisions in Practice.

Network Design in an Uncertain Environment: The Impact of Uncertainty on Network Design, Discounted Cash Flow Analysis, Representations of Uncertainty, Evaluating Network Design Decisions Using Decision Trees "AM Tires: Evaluation of Supply, Chain Design Decisions Under Uncertainty, Risk Management and Network Design, Making Supply Chain Decisions Under Uncertainty in Practice

Modulo 3

Planning Demand and Supply in a Supply Chain: Demand Forecasting in a Supply Chain, The Role of Forecasting in a Supply Chain. Characteristics of Forecasts. Components of aForecast and Forecasting Methods. Basic Approach to Demand Forecasting. Time-SeriesForecasting Methods, Measures of Forecast Error, Forecasting Demand at Tahoe Salt, TheRole of IT in Forecasting. Risk Management in Forecasting, and Forecasting in Practice.

Aggregate Planning in a Supply Chain: The Role of Aggregate Planning in a Supply Chain, the Aggregate Planning Problem, Aggregate Planning Strategies, Aggregate Planning Using Linear Programming, Aggregate Planning in Excel. The Role of IT in Aggregate Planning, Implementing Aggregate Planning in Practice.

Planning Supply and Demand in a Supply Chain: Managing Predictable Variability, Responding to Predictable Variability in a Supply Chain, Managing Supply, Managing Demand, Implementing Solutions to Predictable Variability in Practice.

Module 4

Planning and Managing Inventories in a Supply Chain: Managing Economies of Scale in a Supply Chain, Cycle Inventory, The Role of Cycle Inventory in a Supply Chain, Economies of Scale to Exploit Fixed Costs, Economies of Scale to Exploit Quantity Discounts, Short-Term Discounting.



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Trade Promotions, Managing Multiechelon Cycle Inventory, Estimating Cycle Inventory-Related Costs in Practice.

Managing Uncertainty in a Supply Chain: Safety Inventory, The Role of Safety Inventory in a Supply Chain, Determining Appropriate Level of Safety Inventory, Impact of Supply Uncertainty on Safety Inventory, Impact of Aggregation on Safety Inventory, Impact of Replemshment Policies on Safety Inventory, Managing Safety, Inventory in a Multischelon Supply Chain, The Role of II in Inventory Management, Estimating and Managing Safety Inventory in Practice

Determining the Optimal Level of Product Availability: The Importance of the Level of Product Availability, Factors Affecting Optimal Level of Product Availability, Managerial Levers to Improve Supply Chain Profitability, Setting Product Availability for Midtiple Products under Capacity Constraints, Setting Optimal Levels of Product Availability in Practice

Module 9

Designing and Planning Transportation Networks: Transportation in a Supply Chain, The Role of Transportation in a Supply Chain, Modes of Transportation and Their Performance Characteristics, Transportation Infrastructure and Policies, Design Options for a Transportation Network Trade-Offs in Transportation Design, Tailored Transportation, The Role of fI in Transportation Risk Management in Transportation, Making Transportation Decisions in Practice

Managing Cross-Functional Drivers in a Supply Chain: Sourcing Decisions in a Supply Chain, the Role of Sourcing in a Supply Chain, In-House or Outsource, Third- and Fourth-Party Logistics Providers, Supplier Scotting and Assessment, Supplier Selection-Auctions and Negotiations Contracts and Supply Chain Performance, Design Collaboration, The Procurement Process, Sourcing Planning and Analysis, The Role of IT in Sourcing, Risk Management in Sourcing, Making Sourcing Decisious in Practice.

Text Books:

- Supply Chain Management: Janat Shah, Pearson Publications 2010.
- Supply Chain Management: Sunil Chopra and Mein del, Fourth Edition, PHI 2010.
- Supply Chain Management: A.S. Altekar PHI Second Ed 2006.
- 4. Logistics Management: James Stock and Douglas Lambert. McGraw Hill InternationalEd 2006.
- 5. Supply Chain Management for Global Competitiveness: Ed.B.S. Sahay McMillanPublication 2000.
- Emerging Trends in Supply Chain Management: Ed.B.S. Sahay McMillan Publication 2000.
- 7. Logistics Management: Bowersox TMH 2004.

| Course | Subjects | Periods/Week | | | , | Cyntus | Credits | |
|---------|-------------------------------------|--------------|---|-----|-----|--------|---------|---|
| Code | | L. | T | P | TA. | ESE | Total | |
| | Elective - II | 3 | 0 | 300 | 40 | 60 | 100 | 3 |
| DPPATPI | 4. Advanced Manufacturing Processes | | | | | | | |
| IPPATPS | 5. Mechanics of Sheet Metal Furning | | | | | | | |
| PPATES. | 6. Micro-manufacturing | | | | | | | |



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IPPATP4 Advanced Manufacturing Processes

Course Objectives:

The objective of this course is to

- Provide the in depth knowledge of the types of advanced manufacturing and machining processes (AMPs), evolution, and need.
- Acquire fundamental knowledge and understanding of Production and Industrial Engineering and to know about the applications of advanced manufacturing processes
- 3. Make acquainted the various unconventional manufacturing processes.
- Create a congenial environment that promotes learning, growth and impacts ability to work with multi-disciplinary groups in professional, industry and research organizations
- 5. Encourage the students for developing the models of Advanced Massifacturing Processes.

Course Outcomes:

On completion of this course, the students will be able to

- Categorize different material removal, joining processes as per the requirements of material being used to manufacture end product.
- Select material processing technique with the aim of cost reduction, reducing material wastage & machining time.
- Identify the correct advanced manufacturing processes by formulating and determining the correct AMPs for development of various complex shaped geometries
- Interpret foundry practices like pattern making, mold making. Core making and Inspection of defects.
- 5. Classify different plastic molding processes, Extrusion of Plastic and Thermoforming.
- 6. Select appropriate Joining Processes to manufacture any component.

COURSE CONTENTS

Module 1

Advanced foundry processes - metal mould, continuous, squeeze, vacuum mould, evaporative pattern, and ceramic shell casting:

Module 2

Non-Imditional Machining Introduction, need, AJM, Parametric Analysis, Process capabilities, USM Mechanics of cutting, models, Parametric Analysis, WJM principle, equipment, process characteristics, performance, EDM principles, equipment, generators, analysis of R-C circuits, MRR, Surface frinsh, WEDM.

Module 3

Laser Beam Machining - Principle of working, equipment, Material removal rate. Process parameters, performance characterization, Applications. Electron Beam Machining - Principle of working, equipment, Material removal rate, Process parameters, performance characterization, Applications. Electro Chemical Machining - Principle of working, equipment, Material removal rate, Process.

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parameters, performance characterization, Applications.

Module 4

Advanced forming processes - electro-magnetic forming, explosive forming, electro-hydraulic forming, stretch forming, contour roll forming

Module 5

Advanced welding processes - EBW, LBW, USW

Text Books and References:

- 1. Manufacturing Engineering and Technology by Kalpak Jain, Addison Wesley, 1995.
- Materials and Processes in Manufacturing (8th Edition), E.P. DeGarmo, J. T. Black, R.A. Kohser, Prentice Hall of India, New Delhi (18BN 0-02-978760).
- 3 Advanced Machining Processes by V. K. Jain, Allied Publications
- Manufacturing Science, A. Ghosh, and A.K. Mallik, Affiliated East-West Press Pvt. Ltd. New Dolla.
- Nontraditional Manufacturing Processes, G.F.Benedict, Marcel Dekker, Inc. New York (ISBN 0-8247-7352-7).
- Introduction to Manufacturing Processes by John A Schey, Mc Graw Hill.
- Non-Traditional Manufacturing Processes by Gary F Benedict, CRC Press.
- 8. Advanced Methods of Machining by J. A.Mc Geough, Springer

IPPATP5 MECHANICS OF SHEET METAL FORMING

Course Objectives:

The objective of this course is to

- Develop various metal forming processes
- Generate the concept of plastic deformation during forming processes
- 3. Different laws and equations developed for solving metal forming problems

Course outcomes:

After completion of this course, the student should be able to:

- Generate the concept of different metal forming process.
- Approach metal forming processes both analytically and numerically
- 3. Design metal forming processes
- Develop approaches and solutions to analyze metal forming processes and the associated problems and flaws:

COURSE CONTENTS

Module 1

Classification of forming processes mechanism of metal forming, temperature of metal working, hot working, cold working, friction and lubricants. Rolling of metals: Rolling processes, forces and



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geometrical relationship in rolling, simplified analysis, rolling load, rolling variables, theories of cold and hot rolling, problems and defects in rolling, torque and power calculations.

Module 2

Classification of forging processes, forging of plate, forging of circular discs, open die and closed-die forging forging defects, and powder metallurgy forging. Extrusion: Classification, Hot Extrusion, Analysis of Extrusion process, defects in extrusion, extrusion of tubes, and production of seamless pipes.

Module 3

Drawing of tubes, rods, and wires. Wire drawing dies, tube drawing process, analysis of wire, deep drawing and tube drawing. Sheet Metal forming: Forming methods, Hending, stretch forming, spinning and Advanced techniques of Sheet Metal Forming, Forming limit criteria, and defect in formed parts.

Module 4

HERF, Electromagnetic forming, residual stresses, in-process heat treatment, computer applications in metal forming. Press tool design: Design of various press tools and dies like piercing dies, blanking dies, compound dies and progressive blanking dies, design of bending, forming and drawing dies.

Module 5

Forming methods dies & punches, progressive die, compound die, combination die, Rubber forming, Open back inclinable press (OBI press), piercing, blanking, bending, deep drawing, LDR in drawing, forming limit criterion, defects of drawn products, stretch forming. Roll bending & contouring. Simple problems

Text Books and References:

- 1. Mechanical Metallurgy / G.F. Dieter / Tata McGraw Hill, 1998. III Edition
- 2. Principles of Metal Working / Sunder Kumar
- 3. Principles of Metal Working processes / G.W. Rowe
- 4. ASM Metal Forming Hand book
- 5. Mechanical metallurgy (SI Units), G.E.Dieter, McGraw hill Pub-2001.
- Manufacturing Science, Amithab Gosh &A.K.Malik, East-West press 2001.

IPPATP6 MICRO-MANUFACTURING

Course Objectives:

The objective of this course is to

- 1. To introduce the principles fundamental and process mechanics of uncromachining
- To understand of mechanics at micro level machining.
- To analyze on the mechanical/chemical behavior changes during micromachining/manufacturing.
- 4. To evaluate micro and macro machining, visualize micro machining process:



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To understand application and advancements in the micro machining process.

Course Outcomes:

On completion of this course, the students will be able to

- Acquire knowledge about different micro-machining processes.
- Acquire knowledge about super finishing processes.
- Understand about the capabilities of different micro-manufacturing processes.
- 4. Understand about the capabilities of different advanced micro-manufacturing processes:
- Understand about the capabilities of traditional micro-manufacturing processes.

COURSE CONTENTS

Module 1

Introduction and classification of micromachining, Mechanical type micro machining processes; Abrasive jet micromachining (AJMM), Ultrasonic micromachining, abrasive water jet micromachining (AWJMM)

Module 2

Magneto-rheological funshing (MRF), Magneto-rheological abeasive flow funshing (MRAFF), Magnetic flont polishing (MFP),

Module 3

Chemical and electrochemical type advanced machining processes, Electrochemical micromachining (EDMM), electrochemical micro deburring, Chemical and photochemical micromachining. Abrasive based nano finishing processes, Abrasive flow finishing (AFF), Chemo-mechanical polishing (CMP), Magnetic obtasive finishing (MAF)

Module 4

Thermo electric type micro-machining process, Electric discharge micromachining (EDMM), wire EDM, EDDG, ELID, Laser beam micro-machining (LBMM), Electron beam micromachining (EBMM)

Module 5

Traditional mechanical micro-machining processes. Micro turning, micro milling, micro drilling.

Text Books & References

- 1. Introduction to micromachining, VK Jain, Narosa Publisher, New Delhi 2nd edition.
- 2. Micromachining methods, JA Mc Geough, Champan and Hall, London.
- Micro manufacturing processes, VK Jain CRC Press.
- Advanced machining processes, VK Juin, Allied Publisher New Delhi.



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| Course | Subjects | Periods/Week | | | 1 | Svalnav | Credits | |
|-------------------------------|---|--------------|---|---|-----|---------|---------|---|
| Code | | L | T | P | IA. | ESE | Total | |
| IPPATPT IPPATPS IPPATPS | Elective - III 6. Modeling & Simulation 7. Theory of Vibration 8. Artificial Intelligence | 3 | 0 | | 49 | Ø | 100 | 3 |

IPPATP7 MODELING & SIMULATION

Course Objectives:

The objective of this course is to

- Design the importance of modeling to science and engineering.
- 2 Describe future trends and issues in science and engineering, and identify specific industry related examples of modeling in science and engineering.
- 3. Utilize the modeling Process to identify the key parameters of a model, estimate model outcomes, utilize a computational tool, e.g. MATLAB to implement the model representation of the model, convey the results of the simulation accurately, validate the model with data, and discuss the quality and sources of errors in the model.
- Conduct the transforming of continuous functions and dynamics equations into discrete computer representations.
- Examine mathematical representations of functions Describe and utilize linear and nonlinear functions to model empirical data. Visualize empirical data and the fitting function using a computational tool.

Course Outcomes:

On completion of this course, the students will be able to

- Develop the techniques of modeling in the context of hierarchy ofknowledge about a system
 and develop the capability to apply the same to study systems through available software.
- 2 Analyze different types of simulation techniques:
- Simulate the models for the purpose of optimum control by using software.
- Identify different types of models and simulations, describe the nerative development process
 of a model, and
- Explain the use of models and simulations for hypothesis testing and explain how models link the physical world, the virtual world and the science of prediction.

COURSE CONTENTS

Module 1

Introduction: Definition and components of a system, continuous and discrete systems. Modelling: Concepts of system modeling, types of models, static and dynamic physical models, static and dynamic mathematical models. Simulation: Basics of simulation, Steps in simulation, Discrete event



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system simulation. Advintages and disadvantages of simulation, Decision making with simulation.

Module 2

Statistical Models: Review of terminology and concepts, Useful statistical models, Discrete distributions, Continuous distributions, Poisson process, Empirical distributions, Random numbers, Techniques for random generation. Queuing Models: Characteristics of queuing systems; Queuing motation; Long-run measures of performance of queuing systems, Application of models.

Module 3

System Simulation: Techniques of simulation, Monte Carlo method, Experimental nature of simulation, Distributed lag models, Cobweb models Continuous system models, Analog and Hybrid simulation, Feedback systems, Computers in simulation studies.

Module 4:

Simulation software: Comparison of simulation packages with programming languages, classification of simulation software. Description of a general purpose simulation package. Design of scenario and modules, dialog box, database, animation, plots and output, interfacing with other software, summary of results. Examples with MATLAB/AWESIM/ARENA.

Module 5

Analysis after simulation: Importance of the variance of the sample mean, Procedure for estimating mean and variance, Subinterval method, Replication Method, Regenerative method, Variance reduction techniques, Start up policies, Stopping rules, Statistical inferences, Design of experiments. Verification and validation of simulated models, optimization via simulation. Case studies on application of modeling and simulation in manufacturing systems.

Text books & References:

- Averill M. Shaw, "Simulation Modeling and Analysis", Tata McGmw-Hill, 2007.
- 2. Frank L. Severance, "System Modeling& Simulation-an Introduction", JohnWiley& Sons, 2001.
- 3. Geoffrey Gordon, "System Simulation", Prentice Hall India, 1969.
- 4. Robert E. Shannon, "System Simulation: The Art and Science", Prentice Hall India, 1975.
- Charles M Close and Dean K. Frederick Houghton Mifflin, "Modelling and Analysis of Dynamic Systems: TMH, 1993.
- Allan Carrie, "Simulation of manufacturing", John Wiley & Sons, 1988

IPPATPS THEORY OF VIBRATION

Course Objectives:

The objective of this course is to

- Formulate mathematical models of problems in vibrations using Newton's second law or energy principles.
- 2. Determine a complete solution to the modeled mechanical vibration problems:



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- 3. Correlate results from the mathematical model to physical characteristics of the actual system.
- 4. To be able to mathematically model real-world mechanical vibration problems

Course Outcomes:

On completion of this course, the students will be able to

- Determine the natural frequency of transverse vibrations of the shaft and torsional vibrations of sotor systems.
- Analyze the mathematical modelling of the two degrees of freedom systems and explain about the working principle of vibration absorber.
- Compute the natural frequencies and mode shapes of a multi-degree of freedom system and explain the modal analysis of a vibrating system.
- 4. Select the numerical methods to determine natural frequencies of the beam and rotor systems.
- Describe the vibration measurement by using transducers and vibration exciters.

COURSE CONTENTS

Module 1

Element of vibration system: - hunged mass, stiffness and damping, simple harmonic motion, vector representation Single-degree-offreedomsystem. equation-function-energy-method Newtonlawbased, general solution, free and forced vibration, damped and undamped motion.

Module 2

Damed Vibration, equivalent damping, logarithmic decrement, damping measurement, forced vibration, rotating and reciprocating unbalance, vibration, absorber, Seismicinstruments

Module 3

Transient vibration: - impulse response, Convolution integral, Fourier analysis:

Module 4

Multi degree freedom system, equation of motion, co-ordinate coupling, undamped forced vibration, principalmodes, generalized co-ordinates, semi-definite system, orthogonalty of modes, modal analysis, Lagrange's equation.

Natural frequency numerical solution: - Rayleigh's method, Dunkerley's method, Holzer method,

Transfer matrix, Beration method.

Module 5

Continuous system: Vibrationolistretchedcord,torsional/vibration longitudinal vibration of slender red, lateral vibration of beams, Shear deformation and rotary mertia effect, Rayleigh's quotient, Rayleigh's s-Ritemethod.

Text Books &References

- Tse.S.MorseRRollandT Hinkle JvinE. "MechanicalvibrationstheoryandApplication" Published by Allyn and Bacon.
- Thomson T. Milliam "Theory of vibrations with applications" Prentice Hall of India.



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- HartogDen,J.P. "Mechanicalvibrations" TataMcGrawHills, 4thedition 1956)
- 4. MeirovitchL*elementsofvibarationanalysisMcGrawHills-1956
- 5. Anderson R. A. "Fundamentalsofvibration" Mecmillanpoess 1967
- 6. KbstadN.O. Fundamentalsofvibrationanalysis "McGrawHills-1956
- RobertK, Vicrek "Vibrationanalysis" Publishedby Harper& Row
- Timoshenko S., Young D.H. &lleavev W.Jr. "Vibration problem in engineering 4th ed. New York Willey1974
- Merovitch, L., "Analyticalmethodsinvibration publishedby Macmillan (1967).

IPPATP9 ARTIFICIAL INTELLIGENCE

Course Objectives:

The objective of this course is to

- 1 To impart knowledge about Artificial Intelligence.
- 2. To give understanding of the main abstractions and reasoning for intelligent systems.
- To enable the students to understand the basic principles of Artificial intelligence in various applications.

Course Outcomes:

On successful completion of this course, students will be able:

- Solve basic AI based problems.
- Define the concept of Artificial Intelligence.
- 3. Apply AI techniques to real-world problems to develop intelligent systems.
- Select appropriately from a range of techniques when applementing intelligent systems.

COURSE CONTENTS

Module-1

Introduction to artificial intelligence and intelligent agents, categorization of AI, Production systems and rules for some AI problems: water jug problem, missionaries-cannibals problem etc. Solving problems by searching state space formulation, depth first and breadth first search, iterative deepening.

Module-2

Intelligent search methods, memory restricted variants Heuristic search. Hill climbing, best-first search, problem reduction, constraint satisfaction. Game Playing: Minimus, alpha-beta pruning.

Module-3

Knowledge and reasoning: Propositional and first order logic, semantic networks, building a knowledge base, inference in first order logic, logical reasoning systems Planning: Components of a planning system, goal stack planning, non-linear planning strategies, probabilistic reasoning systems, Baysian networks.



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Module-4

Learning Overview of different forms of learning, Inductive learning, learning decision trees, computationallearning theory, Artificial neural networks, Evolutionary computation; Genetic algorithms, swarm intelligence, particle swarm optimization.

Module-5

Applications: Robotics, Natural language processing etc.

Text & Reference Books

- Rich and Knight, "Artificial Intelligence", 3rd Edition, Tata McGraw Hill, 2014.
- Saroj Kaushik, "Artificial Intelligence", Cengage Learning, 2011.
- 3. Deepak Khemani, "A First Course in Artificial Intelligence", Tata McGraw Hill, 2013.
- 4. S. Russel and P. Norvig, "Al: A modern approach", 3rd Edition, Pearson Education, 2009.

| Course | Subjects | Periods/Week | | | - 1 | (valua) | Credits | |
|---------|---------------------------|--------------|---|---|-----|---------|---------|---|
| Code | | L | T | P | IA | ESE | Total | |
| IPPATC1 | Research Methodology& IPR | 2 | 0 | | | 50 | 50 | 2 |

IPPATCI RESEARCH METHODOLOGY& IPR

Course Objectives

The objective of this course is to

- 1. To familiarize participants with basic of research and the research process.
- To enable the participants with basic understanding of types of data and data collection methods.
- To enable the participants in conducting research work and formulating research synopsis and report.
- 4. To familiarize participosas with IPR.
- To impart knowledge for enabling students to develop data analytics skills and meaningful interpretation to the data sets so as to solve the research problem.

Course Outcomes:

On successful completion of this course, students will be able:

- 1 Understand research problem formulation.
- Analyze research related information
- 3 Follow research ethics
- 4. Understanding that when IPR would take such important place in growth of individuals & nation, it is needless to emphasis the need of information about Intellectual Property.
- 5. Right to be promoted among students in general & engineering in particular.

COURSE CONTENTS

Module 1

Introduction and Design of research: Meaning, objectives and significance of research, types and parameters of research, research process, identification and definition of the research problem,

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definition of construct and variables, pure and applied research design, exploratory and descriptive design methodology, qualitative vs. quantitative research methodology, field studies, field experiments vs. laboratory experiments, research design in social and physical sciences.

Module 2

Data and Methods of Data Collection: Survey, assessment and analysis: data collection, primary and secondary sources of data, Collection of primary data through questionnaire and schedules. Collection of secondary data, processing and analysis of data. Sample survey, simple random sampling, stratified random sampling, systematic sampling, cluster sampling, area sampling and multistage sampling. Pilot survey, scaling techniques, validity & reliability.

Module 3

Data Analysis: Procedure for testing of hypothesis, the null hypothesis, determining levels of significance, type i and it errors, grouped data distribution, measures of central tendency, measures of spread/dispersion, normal distribution, analysis of variance one way, two way, chi square test and its application, students 'T' distribution, non-parametric statistical techniques, binomial test. Correlation and regression analysis – discriminate analysis – factor analysis – cluster analysis, measures of relationship

Module 4

Research report preparation and presentation: Review of literature historical survey and its necessity, layout of research plan, meaning, techniques and precautions of interpretation, types of report sechnical report, popular report, report writing a layout of research report, mechanics of writing a research report. Writing bibliography and references.

Module 5

Nature of Intellectual Property: Patents, Designs, Trade and Copyright, Process of Patenting and Development technological research, innovation, patenting, development International Scenario. International cooperation on Intellectual Property. Procedure for grantsof patents, Patenting under PCT

Reference Books:

- Research in education, By J W Best and J V Kahn, Pearson/ Allyn and Bacon.
- 2. Research Methodology Methods and Techniques, C.K. Kothari, New Age International.
- 3. Design and Analysis of Experiments, D C Montgomery, Wiley.
- Applied Statistics & Probability for Engineers, D C Montgomery & G C Runger, Wiley.
- Management Research Methodology. Integration of Principles, Methods and Techniques, K. N. Krishnaswamy, A.1 Sivakumar and M. Mathiranjan, Pearson Education.

| Course | Subjects | Periods/Week | | | 1 | Symbool | Credits | |
|--------|-------------|--------------|---|---|----|---------|---------|---|
| Code | | L | т | P | IA | ESE | Total | |
| DPALTI | CAD-CAM lab | | | | 30 | 20 | - 590 | 2 |

IFFALTI CAD-CAM LAB

Course Objectives:

The objective of this course is to

- 1. Interpret drawings of machine components
- 2. Prepare assembly drawings both manually and using standard CAD packages



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- 3. Familiarize the students with Indian Standards on drawing practices and standard components
- 4. Gain practical experience in handling 2D drafting and 3D modeling software systems
- 5. Analyze the features of CNC Machine Tool.
- 6. Expose students to modern control systems (Fanne, Stemens etc.,)
- 7. Give exposure to software tools needed to analyze engineering problems.
- 8. Give exposure of different applications of simulation and analysis tools.

Course Outcomes

On successful completion of this course, students will be able:

- Execute steps required for modeling 3D objects by using protrusion, cut, sweep, extrade commends.
- Convert 3D solid models into 2D drawing-different views, sections
- 3. Use isometric views and dimensioning of part models
- 4. Machine simple components on CNC machines
- 5. Use CAM software to generate NC code.

List of Experiments

- Use of commands of any computer aided drafting software package such as AutoCAD, Proengineer, CATIA etc.
- Development of mean driven software for graphics using output primitives and for clipping of graphical entities.
- Design of mechanical parts using geometric transformations such as translation, scaling, rotation, reflection etc.
- 4. Development of software for design of any mechanical element and system.
- 5. Development of software for analysis of one-dimensional element using FEM technique.
- Development of computer program for analysis of mechanical element using FEM for user input values.

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| Course | Subjects | Periods/Week | | | 3 | enthor | Credits | |
|---------|-------------------------|--------------|---|---|-----|--------|---------|---|
| Code | | L | T | P | IA. | ESE | Total | |
| IPPBTT1 | Finite Element Analysis | 3 | 0 | | 40 | 68 | 100 | 3 |

IPPBTT1 FINITE ELEMENT ANALYSIS

Course Objectives

The objective of this course is to:

- 1. Implement the basic concept of Finite Element Analysis (FEA) in structural mechanics.
- Solve 1 D, 2 D and dynamic problems using Finite Element Analysis approach.
- 3 Formulate the design and heat transfer problems with application of FEM.

Course Outcomes

On successful completion of this course, students will be able:

- 1 Implement numerical methods to solve mechanics of solids problems
- Formulate and Solve axially loaded bar Problems.
- Formulate and analyze truss and beam problems.
- Implement the formulation techniques to solve two-dimensional problems using triangle and quadrilateral elements.
- 5. Formulate and solve Axi-symmetric and heat transfer problems.

COURSE CONTENTS

Module I

Progressive development of FEA, nodes and elements, coordinate systems, application to the continuum, discretization of the domain, element shape, node, nodal element and coordinate system, shape functions, degrading technique, governing equations for continuum, pre-processor, processer and post processer.

Module 2

Strain displacement and elemental stiffness matrix, assembling of stiffness equation, boundary conditions and solution, direct approach. Galerkin's and virtual work method, discritisation of structure, analysis of spring, but and trusses elements.

Module 3

Solution of plane stress and plane strain problems, iso-parametric formulations, analysis of beams and rigid frames, bending of thin plates; analysis of shalls.

Module 4



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Navier Solutions of Cross-Ply and angle-ply laminated simply-supported plates, determination of stresses finite element solutions for bending of rectangular laminated plates using CLPT and FSDT, formation of stiffness matrix, formation of load vector, numerical integration, post computation of stresses.

Module 5

Nonlinear Analysis, analysis of material and geometric nonlinear problems, adaptive finite analysis, automatic mesh generation, choice of new mesh, transfers variables.

Text & Reference Books

- 1. Rao S.S., "The Finite Element Method in Engineering", Elsevier Science & Technology.
- 2. Hutton D.V., "Fundamental of Finite Element Analysis", Mc Graw Hills.
- Cook R.D., Malkus, D.S. and Plesha, M.E., "Concepts and Applications of Finite ElementAnalysis", 3rdEd. JohnWiley&Sons.
- BatheK.J., "FiniteElementProcedures" Prentice Hall of India, NewDelhi.
- Huebner K.H. and Thorton, E.A., "The Finite Element Methods for Engineers" John Wiley &Sons.
- Zienewiccz O.C. and Taylor, R.L., "The Finite Element Methods", Vol.1, Vol.2 and Vol.3, McGraw Hill.
- Belytshko, T., Liu, W.K. and Moran, B., Non-linear Finite Elements for Continua and Structures? Mc Graw Hills.

| Code | Subjects | Periods/Week | | | Evaluation | | | Credits |
|---------|----------------------|--------------|---|---|------------|-----|-------|---------|
| | | L | T | P | £A. | ESE | Total | |
| IPPBTT2 | Robotics and Control | 3 | 0 | | 40 | 60 | 100 | 3 |

HPPBTT2 ROBOTICS AND CONTROL

Course Objective

The objective of this course is to;

- 1. Study about mechanism, mechanics and mechanical behavior of the industrial robot.
- Introduce the basic concept of arithmetic formulations and its analysis of the industrial sobot.
- 3. Impart knowledge of kinematic, dynamic and trajectory behavior of the industrial robot.
- 4. Introduce the concept of controller design and the artificial intelligence used in the robotics.

Course Outcomes

On successful completion of this course, students will be able to:

- 1. Learn the basic concept of arithmetic modeling of industrial robots.
- Analysis the forward and inverse kinematic behavior of industrial robots.



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- Understand the dynamic behaviors and trajectory generations of industrial robots.
- 4. Apply the concept of robot control theory and its application in robot controller:
- 5. Explore the concept of artificial intelligence and machine learning algorithms used in robotics.

COURSE CONTENTS

Module 1

Progressive development of robotics, man vs machine, specifications and classifications of industrial robot, robot specifications, links joints and terminology, mobility and degree of freedom, yaw, pitch and roll motion, equivalent angle, work envelop geometries, reach and stroke, repeatability, accuracy and precision, the mechanics and control of mechanical manipulator, operating environment, industrial applications.

Module 2

Spatial descriptions and transformations, coordinates frames matrices and their arithmetic, frame assignment to links, fundamental of rotation and transformation, homogeneous coordinate frame, composite, inverse and skew homogenous transformation, description of position and orientation, Denavit-Hartenberg (D-H) parameters, arm equations, direct kinematic problems of industrial robots, inverse kinematics, algebraic and geometrical methods, inverse kinematic of roll pitch yaw joints, inverse kinematic problems of industrial robots, multiple solutions.

Module 3

Introduction to dynamics force, mertia and energy, principle of inertia tensor, joint velocity of manipulator, kinetic and potential energy of manipulator, Language-Euler formulation, equation of motion, dynamics problems of industrial robots, general description of path planning and trajectory generation, description of cartesian and joint space, manipulator Jacobians and velocity of manipulator, trajectory generation and obstacles avoidance of industrial robot.

Module 4

Introduction and system modeling of manipulator control theory, open loop and close loop control, first order and second order linear system, properties of the dynamic model, linear and nonlinear control techniques, performance and stability of feedback control, Proportional-Derivative (PD)control, Proportional-Derivative-Integral (PID) control, introduction of nonlinear control, multivariable robot control, computed torque control, adaptive control, hybrid control, manipulator interaction with environment, system stability and optimal control, applications and examples.

Module 5

Generation of robot programming languages and software packages, introduction to artificial intelligence, knowledge and reasoning, artificial neural network (ANN) and its applications in robotics, fuzzy logic theories and its applications in robotics. All based techniques for navigation,



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bio impired algorithms, multiple robot coordination, design and application of intelligent controller.

Text Books & References

- 1. Fu K.S., Gonzalez R.C. and Lee C.S.G. "Robotics", McGraw Hill Education India.
- 2. John J. Craig, "Introduction to robotics", Addison Wesley Longman.
- 3. Schilling Robert J., "Fundamentals of Robotics", Prentice Hall of India.
- 4. Nagrath I.J. & Mittal R.K., "Robotics & Control" Tata McGraw Hill.
- 5. Murphy, "Introduction of Al robotics", MIT press.
- Havkin S., "Neural Networks and Learning Machines", Pearson Publisher.
- 7. Yen J. & Langari R., "Fuzzy Logic: Intelligence, Control, and Information", Pearson Publisher.

| Course | Subjects | Periods/Week | | | Evaluation | | | Credite |
|-------------------------------|---|--------------|----|---|------------|-----|-------|---------|
| Code | | L. | T. | P | IA. | ESE | Total | |
| IPPBIFI IPPBIF2 IPPBIF) | Elective - IV L. Green Manufacturing 2. Advance Operation Research 3. Total Quality Management | 3 | 0 | | 40 | 69 | 100 | 3 |

IPPBTP1 GREEN MANUFACTURING

Course Objectives:

The objective of this course is

- The graduates use their tident, self-confidence, knowledge and manufacturing practice which
 facilitate them to presume position of acientific and/or managerial leadership in their career
 paths towards green manufacturing.
- Understand the three pillars of sustainability and how they are manifested in sustainable and green manufacturing.
- Understand the basics of the green manufacturing concepts, strategy, different technology used to implement green manufacturing.
- 4. To create congenial environment that promotes learning, growth and imparts ability to work with inter-disciplinary groups in professional, industry and research organizations.
- Understand Life Cycle Assessment approach to evaluate environmental impacts of product design, manufacturing processes, product use-phase, and product end-of-life.
- To broaden and deepen their capabilities in analytical and experimental research methods, analysis of data, and drawing relevant conclusions for scholarly writing and presentation.
- To provide guidance to students for their choices in research and professional career outlook and to encourage students to take up research.

Course Outcomes:

On successful completion of this course, students will be able:

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- Graduate will demonstrate the ability to design a system, component or process to meet desired needs within realistic constraints such as economic, environmental, social, political, ethocal, health and safety, manufacturability and sustainability.
- Graduate will become familiar with green manufacturing concepts and practices and analyze
 the problems within the domains of Green Manufacturing as the members of multistisciplinary
 teams.
- Graduate will be trained towards developing and understanding the impact of environmental oriented components on global, economic, and societal context.
- 4. Explain the concept and principles of green maintfacturing.
- Plan good housekeeping practices for Industry/other places with concern of safety, hygiene and waste reduction.

COURSE CONTENTS

Module 1

Introduction: Sustainable development, indicators of sustainability, sustainability strategies, sustainable manufacturing, elements of sustainable manufacturing, theory of green manufacturing and its principles, need for green manufacturing, drivers and barriers of green manufacturing.

Module 2

Green manufacturing strategy: Manufacturing strategy, elements of manufacturing strategy, manufacturing out puts, competitive priorities; quality, delivery speed and reliability, cost efficiency, flexibility, order winners and order qualifier, tradeoff, production systems, manufacturing levers, competitive analysis, level of manufacturing capability, framework for formulating manufacturing strategy, implications of green manufacturing for manufacturing strategy.

Module 3

Life cycle approach of green manufacturing: Holistic and total Life-cycle approach, six step methodologies for green manufacturing (6-R approach), life cycle assessment (LCA), elements of LCA – Life Cycle Costing, Eco Labelingturget setting, data collectionand processing, finalevaluation by virtue of criteria, environmental management systems.

Module 4

Green manufacturing technology:Definition of green manufacturing technology and practices, classifications of green manufacturing technology, advantages and disadvantages of implementation of green technology.

Module 5

Lean and Green manufacturing: Introduction, Jean evolution & steps, introduction to Jean manufacturing, definition of Jean manufacturing, Jean vs. green manufacturing similarities and differences.

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Text Books & References

- Cleaner Production: Environmental and Economic Perspectives, Misra Krishna B., Springer, Berlin, Latest edition.
- Environmental Management Systems and Cleaner Production, Dr. Ruth Hillary, Wiley, New York, Latest edition.
- 3. Pollution Prevention: Fundamentals and Practice, Paul L Bishop, TMH.
- Costing the earth, Cairnerss and Francis, Harvard Business School Press 2009.
- The principle of sustainability, Simon Dresner, –Earth Scim publishers (2008).
- Manufacturing strategy: How to formulate and implement a winning plan, Thon Miltenburg, Productivity Press Portland, Oregon-2017.
- 7. Manufacturing strategy , Voss C. A., Chapman & Hall-1992
- Manufacturing the future, Steve Brown, Prentice Hall, 2000.
- 9. Manufacturing strategy, Terry Hill, Homewood, IL- 1989
- Becoming Lean Inside Stories of U.S. Manufacturers, Jeffrey K. Liker, Productivity Press, Portland, Oregon
- G. Atkinson, S. Dietz, E. Neumayer, "Handbook of Sustainable Manufacturing", Edward Elgar Publishing Limited, 2007.
- D. Rodick, "Industrial Development for the 21st Century: Sustainable Development Perspectives", UN New York, 2007.
- Rogers, P.P., Jalal, K.F. and Boyd, J.A., "An Introduction to Sustainable Development", Earth scan, London, 2007.
- P. Lawn, "Sustainable Development Indicators in Ecological Economics", Edward Elgar Publishing Limited.
- S. Asefa, "The Economics of Sustainable Development", W.E. Upjohn Institute for Employment Research, 2005

IPPBTP2 ADVANCE OPERATION RESEARCH

Course Objectives:

The objective of this course is

- To explain the ideas about board education in the techniques and modeling concepts used toanalyze and design complex systems.
- 2. To compile the basic concepts of LPP and various solving techniques.
- To make use of assignment, transportation, inventory and various other techniques.
- To illustrate the connection between basics as well the advance tools of the subject rademoustrate
 the link between theory and its real world.
- 5. To define of single and multi variable optimization muthods with and without constraints



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Course Outcomes

On successful completion of this course. Students will be able to-

- 1. Recall and comprehend the LPP and its formulation with solving techniques.
- 2 Remember, understand and analyze the analytical solution of Simplex method, Assignment problem, Transportation problem and related topics questions with effective manner
- 3. Understanding to apply basics as well the advance tools of the subject to demonstrate the link between theory and its real world applications.
- Explain the overview of historical development and review of optimization techniques:

COURSE CONTENTS

Module I

Introduction, Mathematical formulation of the problem, Graphical Solution methods, Mathematical solution of linear programming problem. Slack and Surplus variables. Matrix formulation of general linear programming Problem.

Module 2

The Simplex Method: Artificial variables, two planes Simplex Method, infessible and unbounded LPPs, alternate optima. Dual problem and duality theorems, dual simplex method and its application in post optimility analysis, Revised Simplex method.

Module 3

Construction and solution of these Models, Hungarian method of solving assignment problem, unbalanced assignment problem, matrix form of transportation problem. Initial basic feasible solution, Balanced and unbalanced transportation problems, u-v method for solving transportation problems Selecting the entering variables, Selecting the leaving variables, Degeneracy in transportation Problem.

Introduction and characteristics of dynamic programming, Mathods of solution to DP.

Quening Models, Elementary quening models, Steady-state solutions of Markovian quening models: M/M/1, M/M/1 with limited waiting space, M/M/C, M/M/C with limited waiting space, M/G/1.

Module 5

Classical Optimization Techniques, Introduction, Review of single and Multivariable optimization methods with and without constraints

Text Books & References

- 1. Operation Research, Theory and Application by J.K. Sharma, Macmillan India
- 2. Quantitative techniques in Management by N. D. Vohra, TMH
- 3. Operations Research by P.K. Gupta and D.S. Hirs, S Chand and Sons
- 4. Operation Research: An Introduction by H.A. Taha
- 5. S. S. Rao, Optimization Techniques, Wiely Eastern

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IPPBTP3 TOTAL QUALITY MANAGEMENT

Course Objectives:

The objective of this course is

- 1. Recognize the basic knowledge of History and Evolution of Quality Control and Management.
- 2. Illustrate the philosophy and core values of Quality Management (QM).
- 3. Developthe concepts and statistical methods employed for assurance of quality in products, processes and systems in an industrial environment.
- 4. Determine the effect of Process Capability Analysis and Introduction of Sampling Plans.
- 5. Apply and analyze the Concept of Reliability and Tagnchi Philosophy for Quality

Course Outcomes:

On successful completion of this course, students will be able:

- Develop conceptual understanding of Quality, Quality cost and value
- Analyze and develop control charts for Statistical Quality Control.
- To apply the knowledge of quality control and its tools for process capability.
- 4. Analyze and develop sampling plans for acceptance sampling.
- 5. Identify the concept of TQM and philosophy of quality leaders.
- 6. Identify failure pattern of product, Reliability and Maintenance.
- 7. Evaluate Reliability and METF and Examine Taguchi Philosophy for Quality improvement.

COURSE CONTENTS

Module 1

Introduction: Quality Control: Definitions, Place of quality control in industries, Quality control organization. Difference between inspection and quality control Economics of Quality systems. Quality Assurance and its manual

Module-2

Statistical Process Control: Sample size and frequency of sampling and control, Design and application of control charts for variable and attribute(X.R.C np. p. u chart). Process capability studies.

Module 3:

Acceptance Sampling: AQL, LQL, Producer's Risk, Consumer's Risk, and Performance Measures of Sampling Plans: OC curve and ASN curve Single sampling plans. Double sampling and sequential sampling plans. Rectifying inspection for lots. Sampling plans for continuousproduction. Selection of sampling plans for different situations. Economics ofacceptance sampling.

Module 4

Total Quality Management: Evolution of total quality management. Historical perspective. Elements



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of TQM: elimination of waste and problem exposure. Totalquality control systems. Demings wheel, Deming 14 points-pros and cons in industrial engineering context, Philip Crosby philosophy, Juran Philosophy, Ishikawa Diagram. Quality function development, Quality circles & ISO 9000. Application of TQM toservice type organizations. Various Quality Awards

Module 5

Reliability: Distributions encountered in controlling Reliability mean time to failure. Exponential failure density, MTTF, Weiball, Failure density, Measurement and Tests, Maintenance and Reliability, Robinst Design and Taguchi Method Taguchi Philosophy for Quality Improvement, Quality Loss Function, Signal-to-Noise Ratio.

Text Books & References:

- Grant E.L. and Leave Worth, Statistical Quality Control, TMH. 1996.
- Amitava Mitra, Fundamentals of Quality Control and Improvement, Wiley, 2016.
- Kapur K.C. and Lumberson, Reliability in Engg. Design Wiley Eastern.
- 4. Junin and Godfrey, Quality Handbook, TMH. 1998
- Jain K.C. and Chitale A.K., Quality Assurance and Total Quality Management, Khanna Publisher, India, 2003.

| Course | Subjects | Periods/Week | | | 1 | (valua) | Credits | |
|---------|--|--------------|---|---|-----|---------|---------|---|
| Code | The same of the sa | L | T | P | LA | ESE | Total | |
| EPPBEP4 | Mechanics of Composite Material Smart Materials and Applications | 3 | 0 | * | 400 | 60 | 100 | 3 |
| IPPBIP | Mechatronics in Manufacturing Systems | | | | | | | |

IPPBTP4 MECHANICS OF COMPOSITE MATERIAL

Course Objectives:

The objective of this course is

- 1. Understand the fundamental properties of composite materials:
- 2 Apply the fundamental principles mechanics of composite materials;
- Apply modern analytical techniques to mechanical systems with composite materials;
- 4 Apply computational techniques to mechanical systems with composite materials;
- 5. Understand the manufacturing processes and cost analysis in composite materials;
- Demonstrate effective communication and teamwork skills through technical presentations and reports in term projects.

Course Outcomes:

On successful completion of this course, students will be able

- Determine composite mechanical properties from constituent fiber and matrix material properties including longitudinal and lateral moduli, Poisson's ratio, and shear modulus.
- Determine the generalized stiffness and compliance matrix relating in-plane stresses to strains for a composite layer assuming plane stiffness.



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- Apply classical laminated plate theory to determine extensional, coupling, and bending stiffnesses of a composite laminate. Also be able to perform this calculation using MATLAB for a composite laminate with many layers.
- Fabricate composite laminates and built-up composite structures such as I-beams, box beams, or model-scale aircraft wings using a composite manufacturing procedure.

COURSE CONTENTS

Module 1

Introduction: Definition of composites, classification of composites. Fibers and matrix
materials and their properties, generalized Hook's law-on hotropic, transversely isotropic and isotropic
materials; constitutive equations under plane stress condition for
orthotropic materials, restrictions on classic constants of orthotropic materials.

Module 2

Macromechanics of Lamina - Stress-strainelations for alumina of arbitrary orientation, invariant properties of an Orthotopic lamina, experimental determination of strength and stiffness. Biaxial strength theories of an Orthotopic lamina: maximum stress theory, maximum strain theory, Tsai-Hill theory, Tsai-Wu Tensor theory.

Module 5

Micromechanics of Lamina - Mechanics of materials approach to stiffness (determination of $E_1, E_2, U_1 \otimes G_{12}$), mechanics of materials approach to strength; tensile and compressive strength in fiber directions, elasticity approach to stiffness, some results of exact solution.

Module 4

Micromechanics of Laminate: - Classical lamination theories (CLT)-laminate stress, laminate stiffness: As B-D matrix and their implication, symmetric and non-symmetric laminates interlaminates ress, limitations of classical lamination theory.

Module 5

Short Fiber Composites: -Theories of stress-transfer, average fiber stress, modulus prediction, strengtherediction, effectof matrioductibity. Ribbon - Reinforced composites

Text & Reference books:

- 1. "Modern Composite Materials" by L. J Broutman and R. M. Krock,
- 2. "Composite Materials Science and Engineering" by K K Chawla,
- 3. "Mechanisms and Mechanics of Composite Fracture" by R. B Bhagat and S G Fishman,
- "An Introduction To Composite Materials" by D Hull, "STRUCTURAL COMPOSITE MATERIALS" by F C Campbell,
- "Composite Materials" by Berthelot, "Electrostatic Discharge Sensitivity of Composite Energetic Materials" by Michelle I. Pantoya and Chelsen Weir

IPPBTPS SMART MATERIALS AND APPLICATIONS



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Course Objectives

The objective of this course is

- Describe different types of smart materials in terms of underlying mechanisms, advantages and disadvantages
- Select the most appropriate smart material system for a design problem under specified design constraints
- Possess a general picture of smart material systems and knowledge about current research areas and future trends.
- 4 Design of sensors and actuators using smeat materials and learn about Energy harvesting using piezoelectric materials
- 5. Describe Magneto theological fluid and its applications.

Course Outcome

On completion of this course, the students will be able to

- Design and construct simple functional structures using smart materials.
- 2. Describe and characterize mechanical behavior of smart materials
- Characterize interaction between smart materials and simple structures in actuation and sensing.
- 4. Describe and characterize novel functions of smart materials using structure-property relationships.
- 5. Present and demonstrate the functions of smart structures.

COURSE CONTENTS

Module 1

Definition of smart materials, what makes them smart, seasons, actuators and transducers; introduction to different types of smart material, Smart materials; history and industrial application

Module 2

Piezoelectric materials – Crystallography and crystal structure, mechanism of piezoelectricity, Common piezoelectric materials, Applications, Derivation of constitutive laws from energy principle and its application as actuator, sensor, and energy harvester.

Superelasticity, superelastic materials phase transformation

Module 3

Shape memory alloys - Martensitic transformations, shape memory effect and super-elasticity, Mechanical behaviour and shape memory characteristics of different shape memory alloy systems, Ti-Ni Phase diagrams

Module 4

Thermally and Magnetically activated Shape memory alloy: constitutive modelling using phenomenological and thermodynamic approaches, its applications as actuator, sensor, energy dissipater, and stent like biomedical items, Design and Application of Shape memory alloys.

Module 5

Magneto rheological fluid: constitutive behaviour and its applications as damper, Behaviour of Electro active polymer and its use as artificial muscles, Properties of Magnetostrictive materials and Optical Fibre.

Text & Reference Books:

- Mel M. Schwartz, Smart Materials, CRC Press, 2009.
- 2. Donald J. Leo, Engineering analysis of smart material systems, John Wiley & Sons, 2007.



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- Jiashi Yang, Analysis of piezoelectric devices, World Scientific, 2006.
- Ralph C. Smith, Smart material systems: model development, siam, 2005.
- Vijay K. Varadan, Smart material systems and MEMS: design and development methodologies, John Wiley & Sons, 2006.
- Seung- Bok Choi & Young-Min Han, Piezoelectric actuators: control applications of smart materials, CRC Press - 2010.
- Antonio Arnau, Piezoelectric transducers and applications, Springer, 2004.

IPPBTP6 MECHATRONICS IN MANUFACTURING SYSTEMS

Course Objectives:

The Objective of this course is

- 1. Understand characteristics and the components of mechatromes systems
- Discuss recent trends in Mechatronics
- 3. Describe active & Passive electrical circuits
- 4. Describe the techniques are of used to design a mechatronics process
- 5 Suggest possible design solutions

Course Outcomes:

On completion of this course, the students will be able to

- Identification of key elements of mechatronics system and its representation in terms of block diagram
- Understanding the concept of signal processing and use of interfacing systems such as ADC, DAC, digital PO
- 3. Interfacing of Sensors: Actuators using appropriate DAQ micro-controller
- 4 Time and Frequency domain analysis of system model (for control application)
- PID control implementation on real time systems
- 6 Development of PLC ladder programming and implementation of real life system.

COURSE CONTENTS

Module 1

Introduction to Mechatronics, Need of Mechatronics in measurement systems, Control systems, Traditional design.

Module 2

Feedback devices, Introduction of sensors and transducers, Performance terminology, Displacement, Positionand proximity, Velocity and motion, Fluid pressure, Temperature sensors - Light sensors, Selection of sensors, Signal processing, Servo systems.

Module 3

Role of microprocessors in Mechatronics, Introduction of microprocessors and microcontrollers. Pin configuration, Instruction set.Programming of microprocessors using 8085 instructions. Interfacing

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With effect from Academic Year 2021-22

input and outputdevices, Interfacing D/A converters and A/D converters. Applications - Temperature control, Stepper motor control. Traffic light controller.

Module 4

Programmable logic controllers(plc) Introduction, Basic structure, Input/output processing, Programming, Mnemonics timers, Internal relays and counters, Data handling, Analog suput/output, Selection of PLC.

Module 5

Design and Mechatronics, Designing, Possible design solutions, Case studies of Mechatronics systems.

Text & Reference Books:

- Histand Michael B. and Alciatore David G., "Introduction to Mechatronies and Measurement Systems", McGraw-Hill International Editions, 1999.
- Bradley, D.A., Dawson, D. Buru, N.C. and Loader, AJ, "Mechatronics", Chapman and Hall, 1993.
- Ramesh S. Gaoukur, "Microprocessor Architecture, Programming and Applications" Wiley Eastern, 1998.
- Lawrence J.Kamm, "Understanding Electro-Mechanical Engineering, An Introduction to Mechatronics", Prentice-Hall, 2000.
- Ghosh P.K. and Sridhar, P.R., "Introduction to Microprocessors for Engineers and Scientists, (0000 to 8085)", Second Edition, Prentice Hall, 2004.

| Course | Subjects | Periods/Week | | | 1 | Ova lina | Credits | |
|----------|------------------------------------|---------------|-----|---|----|----------|---------|---|
| Code | | ${\bf E}_{i}$ | Ť | P | LA | ESE | Total | |
| | Open Elective | 3 | 0 | | 40 | 60 | 200 | 2 |
| MSPRTO1 | 9. Business Analytics | | 177 | | | | | |
| IPPBTO2 | 10. Industrial Safety | | | | | | | |
| IPPRIOS | 11. Operations Research | | | | | | | |
| CEPBTO4 | 12. Cost Management of Engineering | | | | | | | |
| | Projects | | | | | | | |
| MEPBIOS | 13. Composite Materials | | | | | | | |
| CHPSTO6 | 14. Waste to Energy | | | | | | | |
| ECPBTO7 | 15. foT | | | | | | | |
| MCPBTOS. | 16. MOOCs | | | | | | | |

MSPBT01BUSINESS ANALYTICS

Course Objectives:

- 1 Understand the role of business analytics within an organization.
- Analyze data using statistical and data mining techniques and understand relationships between the underlying business processes of an organization.
- To gain an understanding of how managers use business analytics to formulate andsolve business problems and to support managerial decision making.
- 4. To become familiar with processes needed to develop, report, and analyze business data.
- 5. Use decision-making tools/Operations research techniques.



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- 6 Mange business process using analytical and management tools.
- Analyze and solve problems from different industries such as manufacturing, service, retail, software, banking and finance, sports, planmaceutical, serospace etc.

Course Outcomes-

On completion of this course, the students will be able to

- Knowledge of data analytics.
- Think entically in making decisions based on data and deep analytics.
- Use technical skills in predicative and prescriptive modeling to support brainess decisionmaking.
- 4. Translate data into clear, actionable insights

COURSE CONTENTS

Module 1

Business analytics: Overview of Business analytics, Scope of Business analytics, Business Analytics Process, Relationship of Business Analytics Process and organization, competitive advantages of Business Analytics, Statistical Tools: Statistical Notation, Descriptive Statistical methods, Review of probability distribution and data modeling, sampling and estimation methods overview.

Module 2

Trendiness and Regression Analysis: Modeling Relationships and Trends in Data, simple Linear Regression. Important Resources, Business Analytics Personnel, Data and models forBusiness analytics, problem solving. Visualizing and Exploring Data, Business Analytics Technology.

Madule 5

Organization Structures of Business analytics, Team management, Management Issues, Designing Information Policy, Outsourcing, Ensuring Data Quality, Measuring contribution of Business analytics, Managing Changes, Descriptive Analytics, predictive analytics, predictive Modelling, Predictive analytics analysis, Data Mining, Data Mining Methodologies, Prescriptive analytics and its step in the business analytics Process, Prescriptive Modelling, nonlinear Optimization.

Module 4

Forecasting Techniques. Qualitative and Judgmental Forecasting, Statistical Forecasting Models, Forecasting Models for Stationary Time Senes, Ferecasting Models for Time Senes with a Linear Trend, Forecasting Time Series with Sensonality, Regression Forecasting with Casual Variables, Selecting Appropriate Forecasting Models.

Monte Carlo Simulation and Risk Analysis: Monte Carle Simulation Using Analytic Solver Platform, New-Product Development Model, Newswendor Model, Overbooking Model, Cash Budget Model. Module 5

Decision Analysis: Formulating Decision Problems, Decision Strategies with the without Outcome Probabilities, Decision Trees, The Value of Information, Utility and Decision Making.

Module 6

Recent Trends in Embedded and collaborative business intelligence, Visual data recovery, Data Storytelling and Data journalism.

Reference:

1. Business analytics Principles, Concepts, and Applications by Marc J. Schmiederjans, Dam G.

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Schniederjans, Christopher M. Starkey, Pearson FT Press.

Business Analytics by James Evans, persons Education.

IPPBTO2 INDUSTRIAL SAFETY

Modulet

Industrial safety: Accident, causes, types, results and control, mechanical and electricalhazards, types, causes and preventive steps/procedure, describe salient points of factories act1948 for health and safety, wash rooms, drinking water layouts, light, cleanliness, fire guarding, pressure vessels, etc. Safety color codes. Fire prevention and firefighting, equipmentand methods.

Module 2

Fundamentals of maintenance engineering: Definition and aim of maintenanceengineering, Primary and secondary functions and responsibility of maintenance department, Types of maintenance, Types and applications of tools used for maintenance, Maintenance cost& its relation with replacement economy. Service life of equipment.

Module 3

Were and Corrosion and their prevention. West-types, causes, effects, wear reductionmethods, Inbricants-types and applications, Lubrication methods, general sketch, working andapplications, i. Screw down grease cup, ii. Pressure grease gan, iii. Splash lubrication, iv. Gravitylubrication, v. Wick feed lubrication vi. Side feed lubrication, viii. Ring lubrication, Definition, principle and factors affecting the corrosion. Types of corrosion, corrosion preventionmethods.

Missiple 4

Fault tracing: Fault tracing-concept and importance, decision treeconcept, need andapplications, sequence of fault finding activities, show as decision tree, draw decision tree forproblems in machine tools, hydraulic, pneumatic automotive, thermal and electrical equipment's like, I. Any one machine tool, it Pump iii. Air compressor, iv. Internal combustionengine, v. Boiler, vi. Electrical motors, Types of faults in machine tools and their general causes.

Module 5

Periodic and preventive maintenance: Periodic inspection-coacept and need, degressing, cleaning and repaining schemes, overhanding of mechanical components overhanding of electrical motor, common troubles and remodies of electric motor, repaircomplexities and its use, definition, need, steps and advantages of preventive maintenance. Steps procedure for periodic and preventive maintenance of: I Machine tools, it Pumps, it. Aircompressors, iv. Diesel generating (DG) sets Program and schedule of preventive maintenance of mechanical and electrical equipment, advantages of preventive maintenance. Repair cycleconcept and importance

Reference:

- 1. Maintenance Engineering Handbook, Higgins & Morrow, Da Information Services.
- 2. Maintenance Engineering, H. P. Garg, S. Chand and Company.
- 3. Pump-hydraulic Compressors, Andels, Mcgrew Hill Publication.
- Foundation Engineering Handbook, Winterkorn, Hans, Chapman & Hall London.

IPPBTO3 OPERATIONS RESEARCH

Course Outcomes:

At the end of the course, the student should be able to

- 1. Apply the dynamic programming to solve problems of discreet and continuous variables.
- 2 Apply the concept of non-linear programming
- 3. Carry out sensitivity analysis
- Model the real world problem and simulate it.

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COURSE CONTENTS

Module 1

Optimization Techniques, Model Formulation, models, General L.R. Formulation, Simplex Techniques, Sensitivity Analysis, Inventory Control Models

Module 2

Formulation of a LPP - Graphical solution revised simplex method - duality theory - dual simplex method - sensitivity analysis - parametric programming

Module 3

Nonlinear programming problem - Kuhn-Tucker conditions min cost flow problem - max flow problem - CPM-PERT

Module 4

Scheduling and sequencing - single server and multiple server models - deterministic inventory models - Probabilistic inventory control models - Geometric Programming.

Module 5

Competitive Models, Single and Multi-channel Problems, Sequencing Medels, Dynamic Programming, Flow in Networks, Elementary Graph Theory, Game Theory Simulation References:

- 1. H.A. Taha, Operations Research, An Introduction, PHI, 2008
- 2. H.M. Wagner, Principles of Operations Research, PHI, Delhi, 1982.
- 3. J.C. Pant, Introduction to Optimisation: Operations Research, Jain Brothers, Delhi, 2008.
- 4. Hitler Libermann Operations Research: McGraw Hill Pub. 2009
- 5. Pannerselvam, Operations Research: Prentice Hall of India 2010
- Harvey M Wagner, Principles of Operations Research: Prentice Hall of India 2010.

CEPBTO4 COST MANAGEMENT OF ENGINEERING PROJECTS

Course Outcomes:

At the end of the course, students will be able to

- Discuss the cost concepts in the cost management process
- 2 Able to lizzable the projects by the application of project cost control methods.
- 3. Determine all types of costing and carryout the analysis of pricings for profitability.
- 4 Application of PERT/CPM for cost management

COURSE CONTENTS

Module 1

Introduction and Overview of the Strategic Cost Management Process

Module 2

Cost concepts in decision-making; Relevant cost, Differential cost, Incremental cost and Opportunitycost. Objectives of a Costing System; Inventory valuation; Creation of a Database for operational control; Provision of data for Decision-Making.

Module 3

Project meaning, Different types, why to manage, cost overruns centres, various stages of project execution: conception to commissioning. Project execution as conglomeration of technical and nontechnical activities. Detailed Engineering activities. Pre-project execution main clearances and/ocuments. Project team: Role of each member. Importance Project site: Data required with significance.

Project contracts. Types and contents. Project execution Project cost control. Bar charts and Networkdiagram. Project commissioning: mechanical and process

Module 4

Cost Behavior and Profit Planning Marginal Costing, Distinction between Marginal Costing

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andAbsorption Costing, Break-even Analysis, Cost-Volume-Profit Analysis. Various decisionmakingproblems. Standard Costing and Variance Analysis. Pricing strategies: Pareto Analysis. Target costing Life Cycle Costing. Costing of service sector. Just-in-time approach, Material Requirement Planning Enterprise Resource Planning. Total Quality Management and Theory of constraints. Activity-BasedCost Management, Bench Marking; Balanced Score Card and Value-Chain Analysis. Budgetary Control;

Flexible Budgets; Performance budgets; Zero-based budgets. Measurement of Divisional profitabilitypricing decisions including transfer pricing.

Module 5

Quantitative techniques for cost management, Linear Programming, PERT/CPM, Transportation problems, Assignment problems, Simulation, Learning Curve Theory.

Beforencer:

- 1. Cost Accounting A Managerial Emphasis, Prentice Hall of India, New Delhi
- 2. Charles T. Hompren and George Foster, Advanced Management Accounting
- 3. Robert S Kaplan Anthony A. Alkinson, Management & Cost Accounting
- 4. Ashish K. Bhattacherya, Principles & Practices of Cost Accounting A. H. Wheeler publisher
- 5. N.D. Vohm, Quantitative Techniques in Management, Tata McGraw Hill Book Co. Ltd.

MEPBTO5 COMPOSITE MATERIALS

Course outcomes

At the end of the course, students will be able to

- Explain and also implement the composite materials for the required performance based on the characteristics.
- Adopt the composite materials as reinforcements.
- 3. Implement the methods of manufacturing of metal matrix composites
- 4. Adopt the methods of manufacturing of polymer matrix composites
- Evaluate the strength of laminutes:

COURSE CONTENTS

Module 1

INTRODUCTION: Definition - Classification and characteristics of Composite materials.

Advantages and application of composites. Functional requirements of reinforcement and matrix, Effectof reinforcement (size, shape, distribution, volume fraction) on overall composite performance.

Module 2

REINFORCEMENTS: Preparation-layup, curing, peoperties and applications of glass fibers, caebon fibers, Keylar fibers and Boron fibers. Properties and applications of whiskers, particlessinforcements. Mechanical Behavior of composites: Rule of mixtures, Inverse rule of mixtures Isostrain and Isostress conditions.

Module 3

Manufacturing of Metal Matrix Composites: Casting - Solid State diffusion technique,

Cladding - Hot isostatic pressing. Properties and applications. Manufacturing of Cerumic Matrix.

Composites Liquid Metal Infiltration - Liquid phase sintering Manufacturing of Carbon Carboncomposites Knitting Braiding Weaving Properties and applications

Module 4

Manufacturing of Polymer Matrix Composites: Preparation of Moulding compounds and prepares hand layup method - Autoclave method - Filament winding method - Compressionmoulding -Reaction injection moulding. Properties and applications.

Module 5



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Strength: Luminum Failure Criteria-strength natio, maximum stress criteria, maximum straincriteria, interacting fuilure criteria, hygrothermal failure. Luminute first play failure-insight strength; Luminute strength-ply discount transated maximum strain criterion; strength design using caplet plots; stress concentrations.

TEXT BOOKS:

- Material Science and Technology Vol 13 Composites by R.W.Cahn VCH, West Germany.
- Materials Science and Engineering, An introduction. WD Callister, Jr., Adapted by R.

Balasubramaniam, John Wiley & Sons, NY, Indian edition, 2007.

References

- 1. Hand Book of Composite Materials-ed-Lubin.
- 2. Composite Materials K. K. Chawla.
- Composite Materials Science and Applications Deborah D.L. Chung.
- Composite Materials Design and Applications Dunial Guy, Suong V. Hou, and Stephen W. Tasi.

CHBTO6 WASTE TO ENERGY

Course outcomes

- 1. At the end of the course, students will be able to
- Classify the waste for fael and identify the devices for conversion of waste to energy.
- 3. Implement the Biomass Pyrolysis.
- 4 Evaluate the methods of Biomass Gasification and implement their applications.
- 5. To design, construct and operation the Biomass Combustion devices.
- 6 Classify biomass, apply the bio energy systems design and construction.

Module 1

Introduction to Energy from Weste: Classification of waste as fuel – Agro based, Forest residue, Industrial waste - MSW – Conversion devices – Incinerators, gasifiers, digestors

Module 2

Biomass Pyrolysis: Pyrolysis - Types, slow fast - Manufacture of charcoal - Methods - Yields and application - Manufacture of pyrolytic oils and gases, yields and applications.

Module 3

Biomstes Gustification: Gustifiers — Fixed bed system — Downdraft and updraft gastifiers — Fluidized bed gastifiers — Design, construction and operation — Gustifier burner arrangement for thermalheating — Gustifier engine arrangement and electrical power — Equilibrium and kinetic consideration ingustifier operation.

Module 4

Biomass Combustion: Biomass stoves – Improved chillahs, types, some exotic designs, Fixed bed combustors. Types, inclined grate combustors, Fluidized bed combustors, Design, construction and operation – Operation of all the above biomass combustors.

Module 2

Biogas: Properties of biogas (Calorific value and composition) - Biogas plant technology and status - Biomass resources and their classification - Biomass conversion processes - Thermo chemical conversion - Direct combustion - biomass gasification - pyrolysis and liquefaction - biochemical conversion - anaerobic digestion - Types of biogas Plants - Applications - Alcohol production from biomass - Bio diesel production - Urban wasteto energy conversion - Biomass energy programme in India.

References

- 1. Non Conventional Energy, Desai, Ashok V., Wiley Eastern Ltd., 1990.
- Biogas Technology A Practical Hand Book Khandelwal, K. C. and Mahdi, S. S., Vol. I & II, TataMcGraw Hill Publishing Co. Ltd., 1983.
- 3. Food, Feed and Fuel from Biomass, Challal, D. S., IBH Publishing Co. Pvt. Ltd., 1991.
- Biomass Conversion and Technology, C. Y. WereKo-Brobby and E. B. Hagan, John Wiley &Sons, 1996.



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ECPBTO7 INTERNET OF THINGS (IoT)

Course outcomes

- 1. At the end of the course, students will be able to
- Understand the concepts of Internet of Things.
- 3. Analyze hasic protocols in wireless sensor network.
- 4. Design IoT applications in different domain and be able to malyze their performance.
- Flaborate the need for Data Analytics and Security in IoT.
- Understand the concepts of Internet of Things.

COURSE CONTENTS

Module 1

Review of computer communication concepts (OSI layers, components, packet communication, Networks, TCP-IP, sub-netting, IPV4 addressing and challenges). IPV6 addressing, IoT architecture reference layer. Characteristics IoT sensor nodes, Edge computer, cloud and peripheral cloud, single board computers, open source hardware, Examples of IoT infrastructure.

Module 2

Software defined networks, network function variation, difference between SDN and NFV for IoT, Basics of IoT System Management with NETCOZF, YANG-NETCONF, YANG, SNMP NETOPEER.

Module 3

MQTT, UDP, MQTT brokers, publish subscribe modes, HTTP, COAP, XMPP and gateway protocols, InT Communication Pattern, InT Protocol Architecture, Selection of Wireless technologies (SLoWPAN, Zighee, WIFI, BT, BLE SIG, NFC, LORA, Lift, With).

Module 4

An Introduction to Data Analytics for IoT, Machine Learning, Big Data Analytics Tools and Technology, Edge Strenning Analytics, Network Analytics, Securing IoT, A Brief History of IOT Security, Common Challenges in IOT Security, How IT and OT Security Practices and Systems Vary, Formal Risk Analysis Structures: OCTAVE and FAIR, The Phased Application of Security in an Operational Environment.

Module 5

In Physical Devices and Endpoints: Introduction to Acdumo and Respherry Pr. Installation, Interfaces (serial, SPI, I2C), Programming – Python program with Raspberry PI with focus on interfacing external gadgets, controlling output, and reading input from pins.

LoT Physical Servers and Cloud Offerings: Introduction to Cloud Storage models and communication APIs WebServer: Web server for IoT, Cloud for IoT, Python web application framework Designing a RESTful web API.

IoT application and its Variants: Case studies: IoT for anort cities, amort grid, health care, agriculture, smart meters M2M, Web of things, Cellular IoT, Industrial IoT, Industry 4.0,IoT standards.

References:



Guru Ghasidas Vishwavidyalaya (Consilared) Stationally be (Intelligence in 2003), 21-41000 Koni, Bilaspur – 495009 (C.G.)

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- "Internet of Things A Hands-on Approach", ArshdeepBahga and Vijay Madisetti, Universities Press, 2015, ISBN: 9788173719547
- "Internet of Things", Srinivasa K. G. CENGAGE Lenning India, 2017.
- "IoT Fundamentals Networking Technologies, Protocols, and Use Cases for the Internet of Things", David Hanes, Gonzalo Salgueiro, Patrick Grossetete, Robert Barton, Jerome Henry1stEdition, Penrson Education (Cisco Press Indian Reprint), (ISBN 978-9386873743)
- "Getting Started with Raspberry Pr", Matt Richardson & Shawn Wallace, O'Reilly (SPD), 2014, ISBN: 9789350239759.
- "From Machine to Machine to Internet of Things", Jan Holler, VlasiosTsiatsis, Catherine Mulligan, Stamatis Karnouskos, Stefan Avesand, David Boyle, Elsevier Publications, 2014.

| Course | Subjects | Periods/Week | | | - 1 | valua | Credits | |
|---------|---------------------------------------|--------------|---|---|-----|-------|---------|---|
| Code | | L | T | P | LA | ESE | Total | |
| | Audit Course/Value Added Course | 3 | 0 | | 40 | 60 | 200 | 3 |
| ELPRIXI | English for Research Paper Writing | | | | | | | |
| PEPBIX3 | Stress Management by Yoga | | | | | | | |
| CEPBEAU | Disaster Management | | | | | | | |
| LAPBTN4 | Constitution of India | | | | | | | |

ELPBTX1 ENGLISH FOR RESEARCH PAPER WRITING

Course outcomes:

At the end of the course, students will be able to

- 1. Understand that how to improve your writing skills and level of readability.
- 2. Lemm about what to write in each section
- 3. Understand the skills needed when writing a Title-

COURSE CONTENTS

Module I

Planning and Preparation, Word Order, Breaking up long sentences, Structuring Paragraphs and Sentences, Being Concise and Removing Redundancy, Avoiding Ambiguity and Vagueness

Module 2

Clarifying Who Did What, Highlighting Your Findings, Hedging and Criticising, Paraphrasing and Plagiarism, Sections of a Paper, Abstracts, Introduction.

Module 3

Review of the Literature, Methods, Results, Discussion, Conclusions, The Final Check, key skills are needed when writing at Alstract, key skills are needed when writing an Alstract, key skills are needed when writing an Introduction, skills needed when writing a Review of the Literature.

Module 4

Skills are needed when writing the Methods, skills needed when writing the Results, skills are needed when writing the Discussion, skills are needed when writing the Conclusions.

Module 5

Useful phrases, how to ensure paper is as good as it could possibly be the first-time submission.

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Suggested Studies:

- Goldbort R (2006) Writing for Science, Yale University Press (available on Google Books).
- Day R (2006) How to Write and Publish a Scientific Paper, Cambridge University Press
- Highman N (1998), Handbook of Writing for the Mathematical Sciences, SIAM. Highman'sbook.
- Adrian Wallwork, English for Writing Research Papers, Springer New York Dordrecht Heidelberg London, 2011

PEPBTX2STRESS MANAGEMENT BY YOGA

Course Outcomes

At the end of the course, students will be able to

- 1. To achieve overall health of body and mind.
- 2. To overcome stress.
- 3 Develop healthy mind in a healthy body thus improving social health also
- 4. Improve efficiency

Module 1

Definitions of Eight parts of yog. (Ashtanga)

Module 2

Yam and Niyam.

Do's and Don't's in life.

- i) Ahinsa, satya, astheya, brambacharya and aparigraha
- ii) Shuucha, santosh, tapa, swadhyay, ishwarpranidhan

Module 3

Asan and Pranayam.

Various yog poses and their benefits for mind & body

ii)Regularization of breathing techniques and its effects-Types of pranayam

Suggested reading

- L. 'Yogic Asanas for Group Tarining-Part-I' : Janardan Swami Yogabbyasi Mandal, Nagpur
- "Rajayoga or conquering the Internal Nature" by Swami Vivekananda, AdvaitsAshrama (Publication Department), Kolkota

CEPBTX3 DISASTER MANAGEMENT

Course Outcomes:

At the end of the course, students will be able to

- Learn to demonstrate a critical understanding of key concepts in disaster risk reductionand humanitarian response.
- Critically evaluate disaster risk reduction and humanitarian response policy and practice from multiple perspectives.
- Develop an understanding of standards of humanitarian response and practical relevancein specific types of disasters and conflict situations.
- 4. Critically understand the strengths and weaknesses of disaster management approaches, planning and programming in different countries; particularly their home country or the countries they work in.

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COURSE CONTENTS

Module 1

Introduction Disaster Definition, Factors And Significance; Difference Between Hazardand Disaster, Natural And Manmade Disasters: Difference, Nature, Types And Magnitude.

Module 2

Repercussions Of Disasters And Hazards: Economic Damage, Loss Of Human And Animal Lafe, Destruction Of Feosystem: Natural Disasters: Earthquakes, Volcomiums, Cyclones, Tsanamis, Floods, Droughts And Famines, Landslides And Avalanches, Man-made disaster: Nuclear Reactor Melidown, Industrial Accidents, Oil Slicks And Spills, Outbreaks Of Disease And Epidemics, War And Conflicts.

Module 3

Disaster Prone Areas In India Study Of Seismic Zones; Areas Prone To Floods And Droughts, Landalides And Avalanches, Areas Prone To Cyclonic And Coastal Hazards WithSpecial Reference To Tsunama, Post-Disaster Diseases And Epidemics

Module 4

Disaster Preparedness And Management Preparedness: Monitoring Of Phenomena Triggering A Disaster Or Hazard, Evaluation Of Risk: Application Of Remote Sensing, Data FromMeteorological And Other Agencies, Media Reports: Governmental and Community Preparedness.

Module 5

Risk Assessment Disaster Risk Concept And Elements; Disaster Risk Reduction, Global AndNational Disaster Risk Situation. Techniques Of Risk Assessment, Global Co-Operation In Risk Assessment And Warning, People's Participation In Risk Assessment Strategies for Survival.

Module 6

Disaster Mitigation Meaning, Concept And Strategies Of Disaster Mitigation, Emerging Trends In Mitigation. Structural Mitigation And Non-Structural Mitigation, Programs Of Disaster Mitigation In India.

SUGGESTED READINGS:

- R. Nishith, Singh AK, "Disaster Management in India: Perspectives, issues and strategies "'New Royal book Company.
- Sahni, Pardeep Et Al. (Eds.)," Disaster Mitigation Experiences And Reflections", Prentice Hall Of India, New Delhi.
- Goel S. L., Disaster Administration And Management Text And Case Studies", Deep&Deep Publication Pvt. Ltd., New Delhi.

LAPBEX4 CONSTITUTION OF INDIA

Course Objectives:

Students will be able to:

- Understand the premises informing the twin themes of liberty and freedom from a civil rights
 perspective.
- 2 To address the growth of Indian opinion regarding modern Indian intellectuals constitutional tole and entitlement to civil and economic rights as well as the emergence of nationhood in the early years of Indian nationalism.
- To address the role of socialism in India after the commencement of the Bolshevik Revolution in 1917 and its impact on the initial drafting of the Indian Constitution.

Course Outcomes



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At the end of the course, students will be able to

- Discuss the growth of the demand for civil rights in India for the bulk of Indians before the arrival of Gandhi in Indian politics.
- Discuss the intellectual origins of the framework of argument that informed the conceptualization of social reforms leading to revolution in India.
- Discuss the circumstances surrounding the foundation of the Congress Socialist Party [CSP] under the leadership of Jawaharlai Nehru and the eventual failure of the proposal of direct elections through adult suffrage in the Indian Constitution.
- Discuss the passage of the Hinda Code Bill of 1956.

COURSE CONTENTS

- History of Making of the Indian Constitution: History Drafting Committee, (Composition & Working).
- Philosophy of the Indian Constitution: Preamble, Salient Features
- Contours of Constitutional Rights & Dunes, Fundamental Rights, Right to Equality, Right to Freedom,
 Right against Exploitation, Right to Freedom of Religion, Cultural and Educational Rights, Right to
 Constructional Remedies, Directive Principles of State Policy, Fundamental Duties.
- Organs of Governance: Purhament, Composition, Qualifications and Disqualifications, Powers and
 Functions, Executive, President, Governor, Council of Ministers, Indictory, appointment and Transfer of
 Judges, Qualifications, Powers and Functions.
- Local Administration: District's Administration head: Role and Importance, Municipalities
 Entroduction, Mayor and role of Elected Representative, CEO of Municipal Corporation, Packayati raj:
 Entroduction, PRE ZilaPachayat: Elected officials and their roles, CEO ZilaPachayat: Position and role.
 Block level: Organizational Hierarchy (Different departments), Village level: Role of Elected and
 Appended officials, Importance of grass root democracy.
- Election Commission: Election Commission: Role and Functioning. Chief Election Commissioner and Election Commissioners, State Election Commission: Role and Functioning. Institute and Bodies for the welfare of SC/ST/OBC and women.

References:

- The Constitution of India, 1950 (Bare Act), Government Publication.
- · Dr. S. N. Busi, Dr. B. R. Ambediar framing of Indian Constitution, 1st Edition, 2015.
- M. P. Jain, Indian Constitution Law, 7th Edn., Lexis Nexis, 2014.
- D.D. Hasti, Introduction to the Constitution of India, Lexis Nexis, 2015.

| Course Code | Subjects | Periods/Week | | 1 | valua | Credits | | |
|----------------|--------------|--------------|---|---|-------|---------|-------|---|
| | | L | T | P | IA | ESE | Total | |
| IPPBPT1 | Mini Project | 3 | 0 | 0 | 40 | 60 | 100 | 3 |

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IPPBPT1 MINI PROJECT

Course Objectives:

The Objective of this course is

- To develop design skills according to a Conceive-Design-ImplementOperate (CDIO) compliant methodology.
- To implement engineering skill and knowledge to complete the identified project work while encouraging creativity and innovation.
- To develop spirit of team work, communication skills through group-based activity and foster self-directing learning and critical evaluation.

Course Outcomes:

On completion of this course, the students will be able to

- I. Identify a problem based on the need analysis of community /industry/ research.
- 2. Create a flowchart of methodology for solving the identified problem
- 3 Demonstrate team work with work division, team meetings and communications among team members.
- 4. Write technical report for the project work and present the same through power point presentations or posters

| Course | Subjects | Periods/Week | 1 | Swithout | Credits | | | |
|---------|--------------|--------------|---|----------|---------|-----|-------|---|
| Code | | I. | T | P | 1A | ESE | Total | |
| IPPBLT1 | Robotics Inh | 3 | | | 40 | 60 | 200 | 3 |

IPPBLT1 ROBOTICS LAB

Course Objectives:

The Objective of this course is

- 1. Learn about force and torque sensing
- 2. Learn about application of robot
- Apply the basic engineering.
- 4. The drive systems used in Industrial applications.
- 5 Simulation Software for Industrial Robota

Course Outcome:

On completion of this course, the students will be able to

At the end of this course, students will demonstrate the ability to

- 1. Develop Ladder diagrams for PLC Programming.
- 2. Work with simple Automation Systems using PLC
- 3. Analyze Forward and Inverse Kinematics for Basic Robots
- 4. Programming and Analysis of Industrial Robots using Software
- 5. Visualize the configurations of various types of robots.

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Describe the components of robots like arms, linkages, drive systems and end effectors.

List of Experiments:

- (1) Assignment on introduction to robot configuration
- (2) Demonstration of robot with 2 dof, 3 dof, 4 dof etc.
- (3) Two assignments on programming the robot for applications
- (4) Two assignments on programming the robot for applications
- (5) Two programming exercises for robots-
- (6) Two case studies of applications in industry
- (7) Exercise on robotic simulation software